

7th HICUM Workshop 2007

**A new transit time extraction algorithm
based on matrix deembedding techniques**

C. Raya, N. Kauffmann, D. Celi, T. Zimmer



Introduction

▣ **T_F importance:**

- T_F physical information from S parameters
- T_F necessary to extract all high injection model parameters
- T_F more convenient than using F_T (Effects of transit time and capacitances decoupled)
- Less computational effort for extraction / optimization

▣ **Brief review of a few existing methods:**

- Conventional method based on $1/(2.\pi.F_T)$
- Methods based on de-embedding techniques

▣ **Objective:**

- Accurate transit time extraction including the saturation at high injection
- Focus on the deep saturation region especially for advanced BiCMOS technologies
- Figures of merit to help improve extraction strategy (e.g. T_{BVL} & D_{TOH} extraction, capacitance behavior in the forward region)

Outline

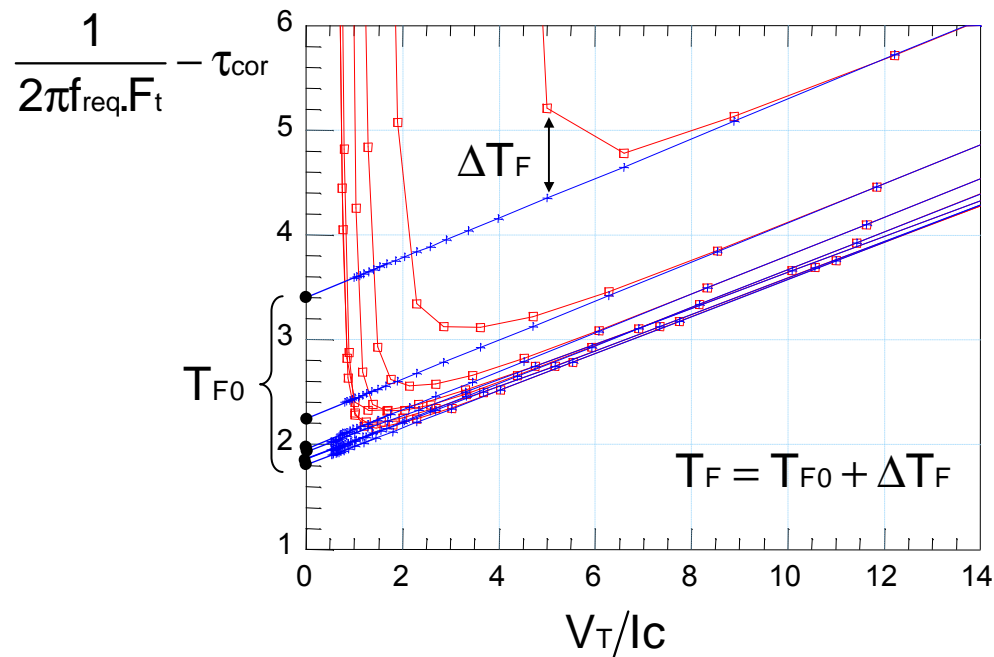
- ▣ I – State of art
- ▣ II – Improved Transit time extraction method
- ▣ III – Extraction Results
- ▣ IV - Conclusion

▣ I – State of art

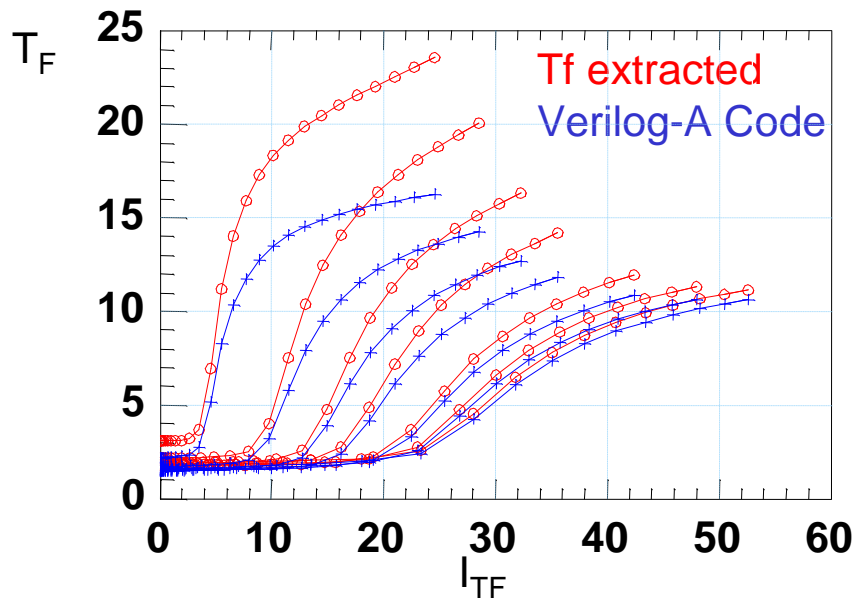
Conventional method: tangent method

$$\frac{1}{2\pi f_{\text{req}} \cdot F_t} - \tau_{\text{cor}} = T_F + (C_{\text{BC}} \cdot (1 + 1/\beta_0) + C_{\text{BE}}) \cdot \frac{1}{g_m} \quad \text{with} \quad g_m \approx \frac{I_c}{m_c \cdot V_T}$$

$$\tau_{\text{cor}} = (r_E + r_{\text{CX}}) \cdot C_{\text{BC}} \cdot (1 + 1/\beta_0)$$



Conventional method: tangent method



$V_{bc}=0.6V, 0.4V, 0.2V, 0V, -0.5V, -1V, -1.5V$

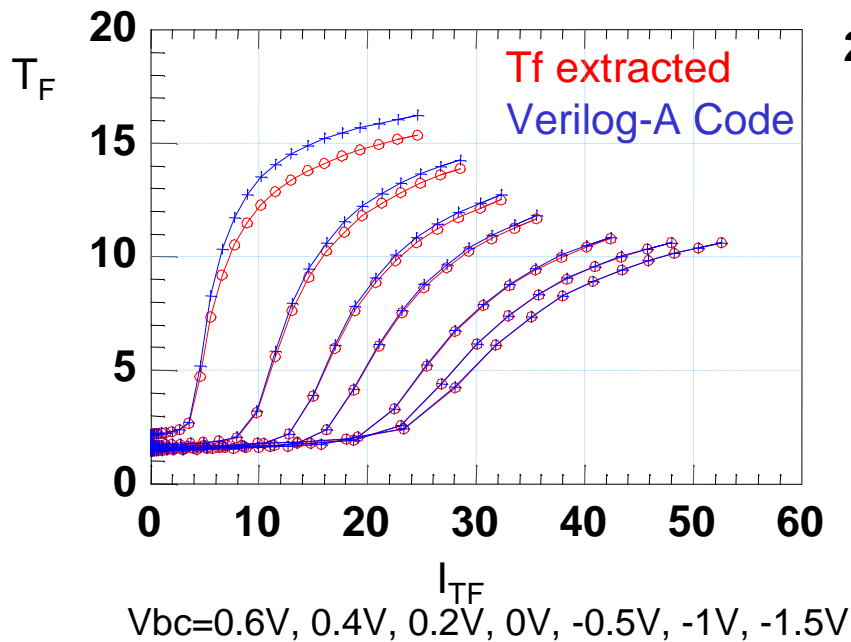
- + Robust at low injection, although it gives effective extracted parameters
- T_F extraction not accurate especially at high injection and in the saturation region
- Bad g_m approximation

M. Malorny, M. Schröter

“Analytical method for calculating elements of an arbitrary equivalent circuit”, MIXDES 2004, Poland, pp.79-84

Z. Huszka

“A Pragmatic Yet Accurate Transit Time Extraction Method for HICUM”, Private communication



2 Methods based on de-embedding techniques

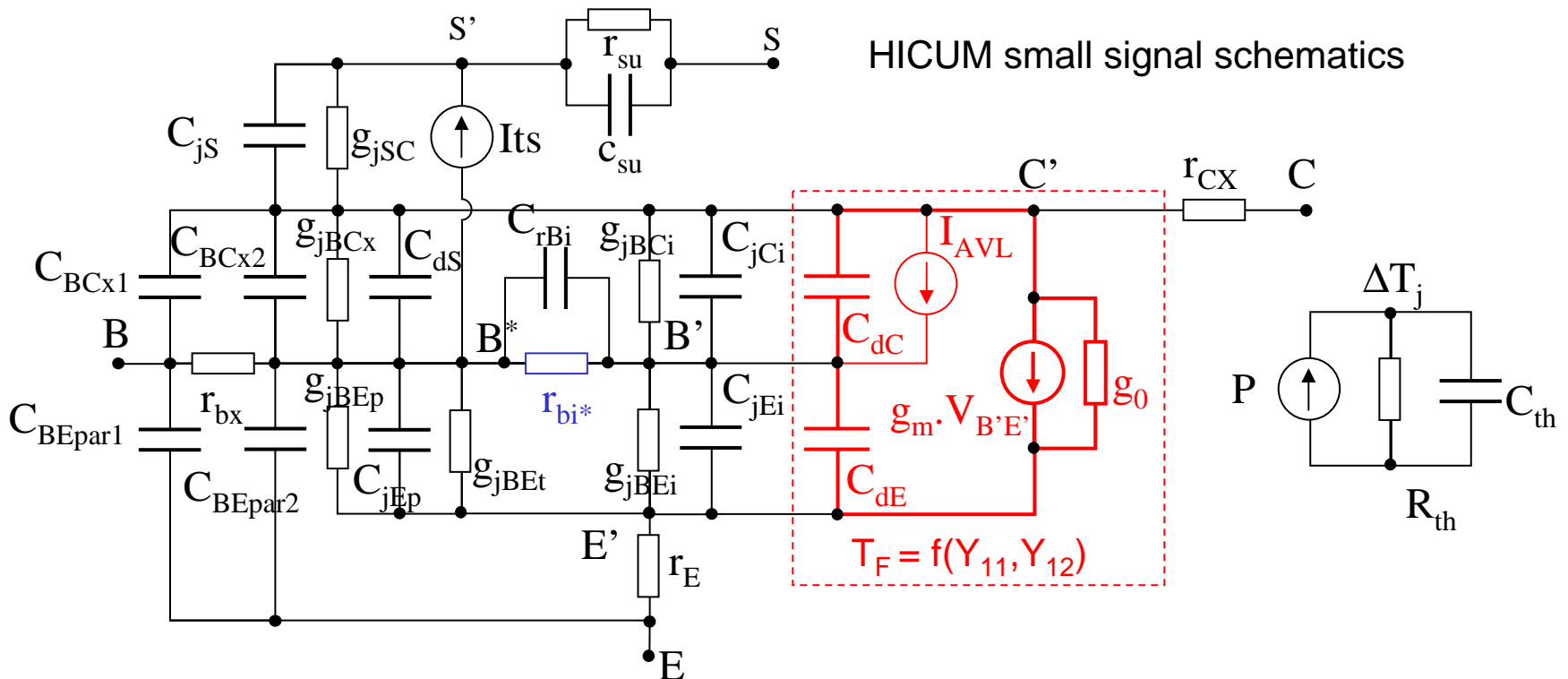
- + Good determination of g_m and g_0
- + Accurate T_F extraction
- The saturation involves a small error for the high injection region.
- Requires a very good accuracy of the capacitances C_{BE} and C_{BC}

The new suggested method is an improvement of this approach



 II – Improved transit time extraction method

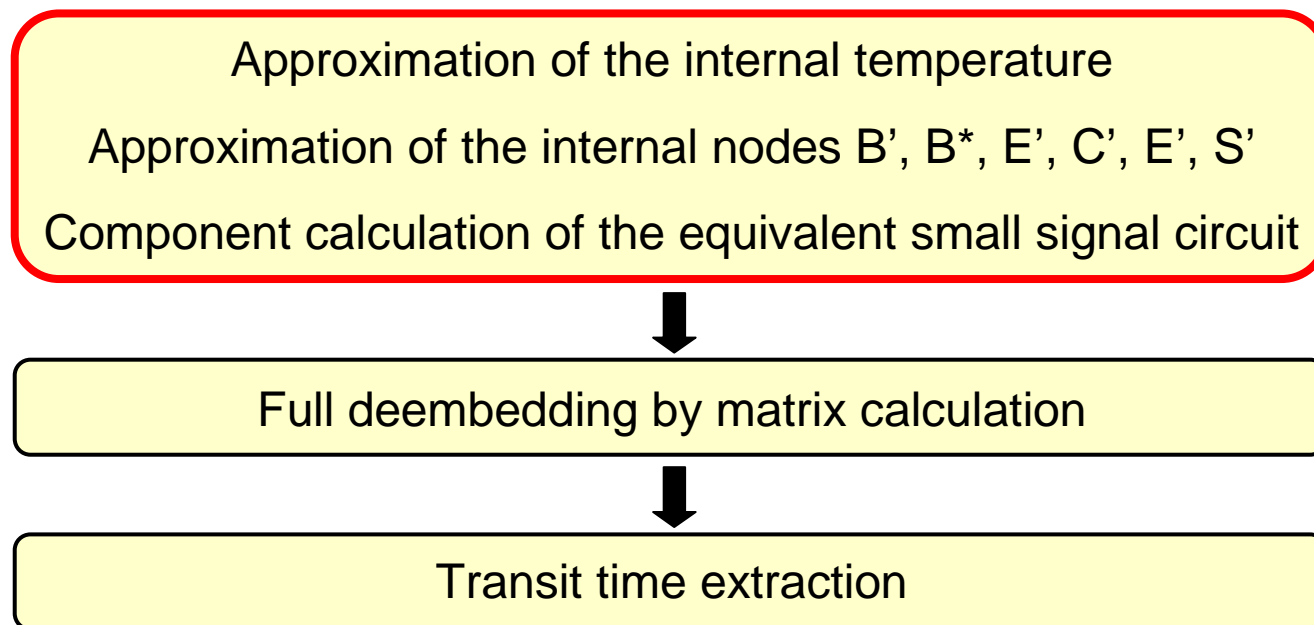
Strategy: Access to the T_F dependent main circuit



Access to the T_F dependent circuit by deembedding techniques requires to determine:

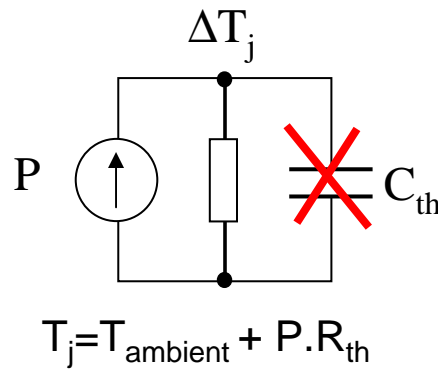
- ▶ The temperature
- ▶ The internal nodes
- ▶ Calculate all bias dependant components of the small signal circuit

▣ II – Improved transit time extraction method

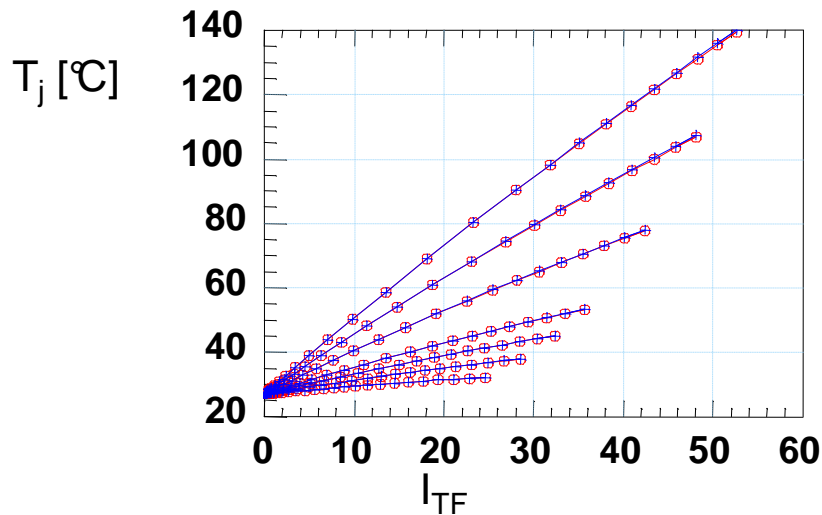


Temperature

Extraction from S-parameters measurement => Small signal => C_{th} could be neglected



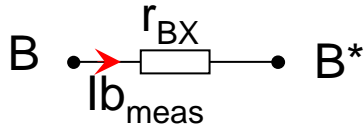
$F_{LSH}=0$	$P=I_{c_{meas}}$
$F_{LSH}=1$	$P \approx I_{c_{meas}} \cdot (V_{CE} - R_E \cdot (I_{c_{meas}} + I_{b_{meas}}) - R_{CX} \cdot I_{c_{meas}})$
$F_{LSH}=2$	$P_1 = I_{b_{meas}} \cdot (V_{BE} - R_E \cdot (I_{c_{meas}} + I_{b_{meas}}))$ $P_2 = I_{c_{meas}} \cdot (V_{CE} - R_E \cdot (I_{c_{meas}} + I_{b_{meas}}) - R_{CX} \cdot I_{c_{meas}})$ $P_3 = R_E \cdot (I_{c_{meas}} + I_{b_{meas}})^2$ $P \approx P_1 + P_2 + P_3$

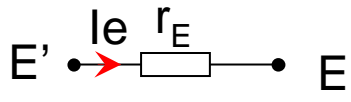


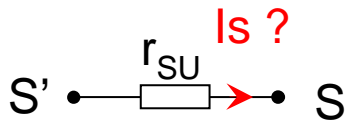
Temperature approximation
Verilog-A Code

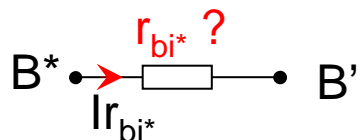
Approximation of the internal nodes


 $V_{C'} = V_C - r_{CX}(T_j) \cdot I_{C_{meas}}$

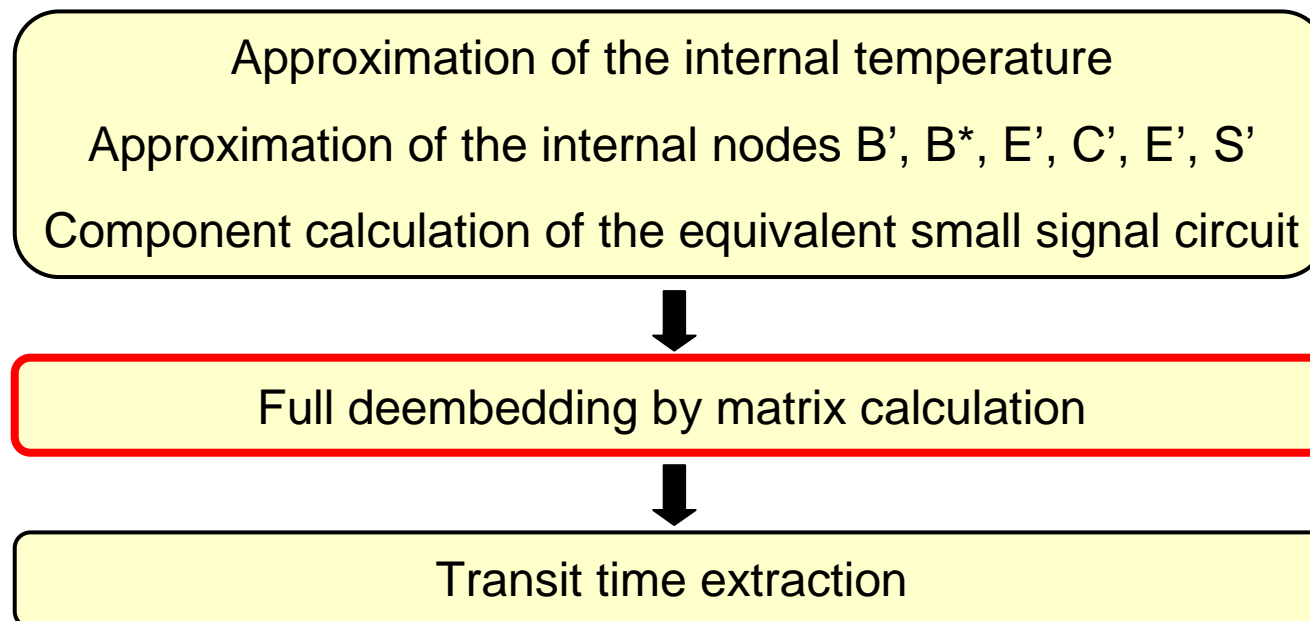

 $V_{B^*} = V_B - r_{BX}(T_j) \cdot I_{b_{meas}}$


 $I_e \approx I_{b_{meas}} + I_{c_{meas}}$ (Structure RF common emitter => I_e is not measured)
 $V_{E'} = V_E + r_E(T_j) \cdot (I_{b_{meas}} + I_{c_{meas}})$


 $I_s ?$
 For $V_{BC} < 0.5V$ the substrate current (I_s is not measured) is low ($V_{SS'} \approx 0V$).
 $V_{S'}$ is assumed equal to V_S (involving an error on the calculation of $V_{S'C'}$ and $V_{S'B^*}$)

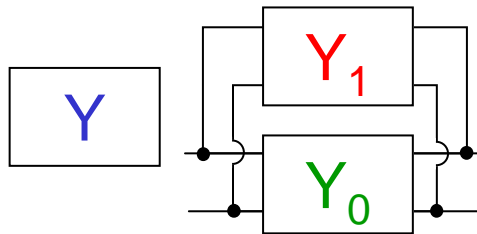

 $I_{r_{bi^*}} = I_{b_{meas}} - I_{jBCX} - I_{jBEP} - I_{ts} - T_{UNODE} \cdot I_{BEtp}$
 $V_{B'} = V_{B^*} - I_{r_{bi^*}} \cdot r_{bi^*}$
 r_{bi^*} calculated for a self-consistent algorithm

▣ II – Improved transit time extraction method



Deembedding

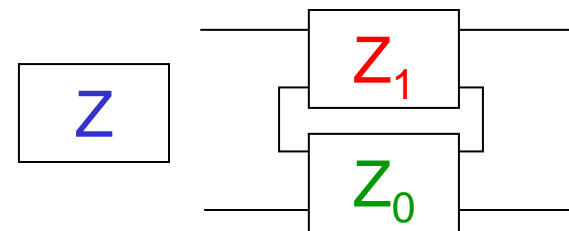
Y Matrix



$$[Y] = [Y_0] + [Y_1]$$

$$[Y_0] = [Y] - [Y_1]$$

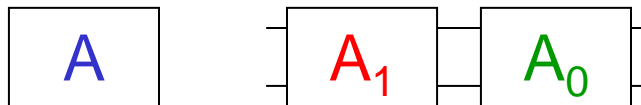
Z Matrix



$$[Z] = [Z_0] + [Z_1]$$

$$[Z_0] = [Z] - [Z_1]$$

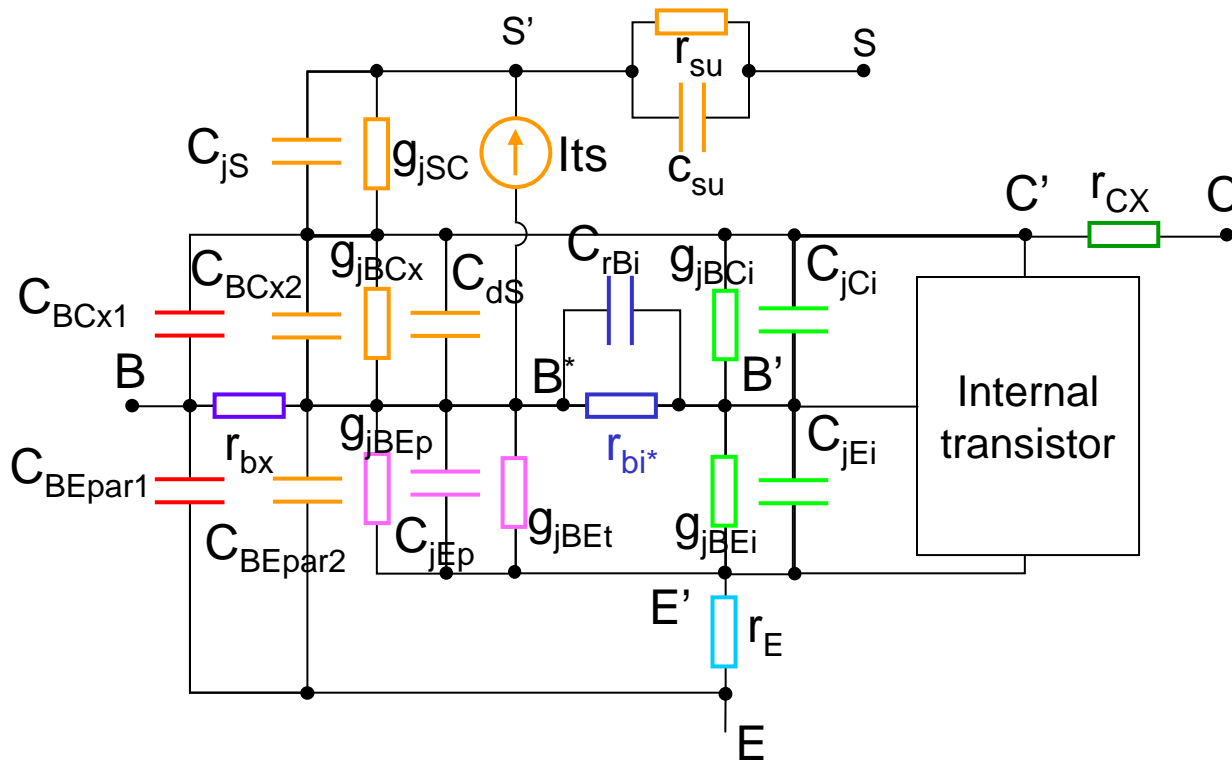
A Matrix



$$[A] = [A_1] \cdot [A_0]$$

$$[A_0] = [A_1]^{-1} \cdot [A]$$

Full deembedding



A Step1

Y Step2

A Step3

Y Step4

Z Step5

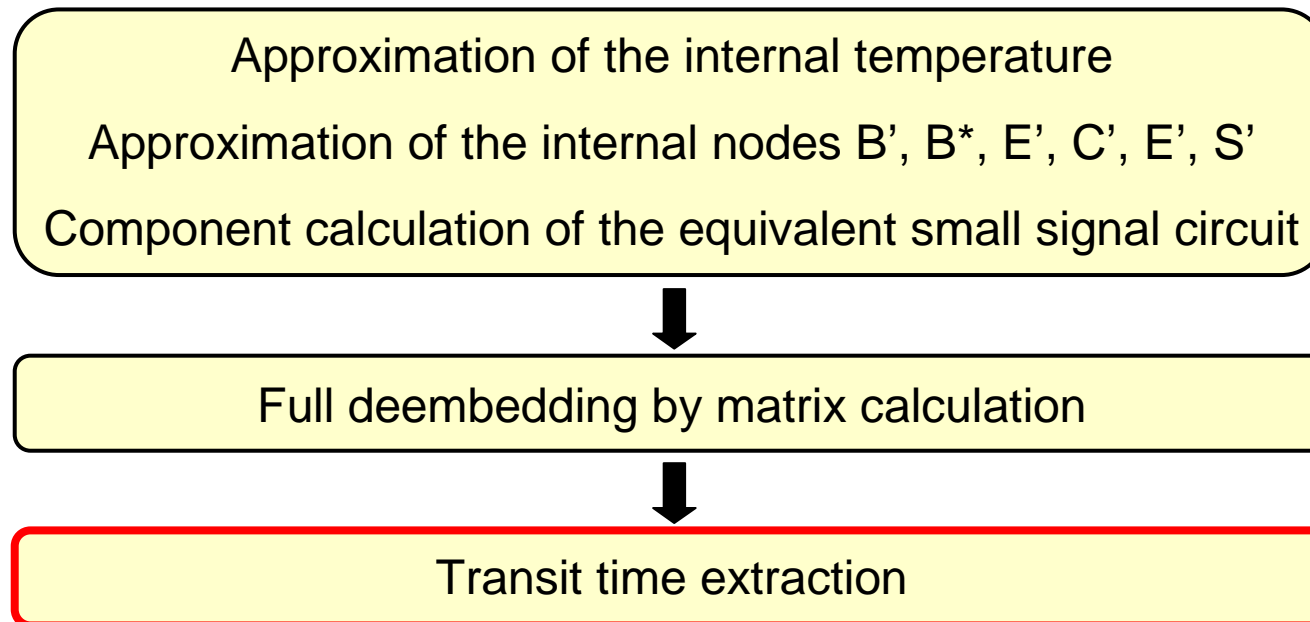
Y Step6

A Step7 (*)

Y Step8

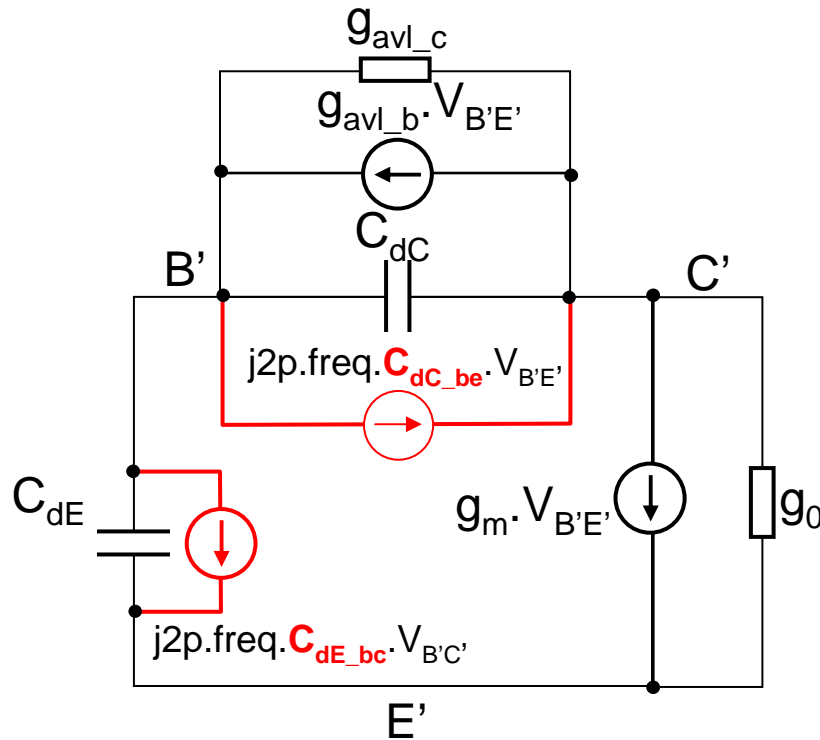
(*) r_{bi^*} is deembedded as a passive resistance (r_{bi^*} is bias dependent)
 Different approaches available to compute r_{bi^*} : calculation, extraction, ...

▣ II – Improved transit time extraction method



Y matrix (from HICUM Verilog-A code)

$$\begin{bmatrix} g_{avl_c} + g_{avl_b} + 2\pi \cdot \text{freq.} \cdot (C_{dE} + C_{dE_bc} + C_{dC_be} + C_{dC}) & -g_{avl_c} - j \cdot 2 \cdot \pi \cdot \text{freq.} \cdot (C_{dE_bc} + C_{dC}) \\ g_m - g_{avl_c} - g_{avl_b} - j \cdot 2 \cdot \pi \cdot \text{freq.} \cdot (C_{dC} + C_{dC_be}) & g_0 + g_{avl_c} + j \cdot 2 \cdot \pi \cdot \text{freq.} \cdot C_{dC} \end{bmatrix}$$



$$\partial Q_f = C_{dE} \cdot \partial V_{B'E'} + C_{dE_bc} \cdot \partial V_{B'C'}$$

$$\partial Q_r = C_{dC} \cdot \partial V_{B'C'} + C_{dC_be} \cdot \partial V_{B'E'}$$

$$C_{dE} = \left. \frac{\partial Q_f}{\partial V_{B'E'}} \right|_{V_{B'C'}=cte} \quad C_{dE_bc} = \left. \frac{\partial Q_f}{\partial V_{B'C'}} \right|_{V_{B'E'}=cte}$$

$$C_{dC} = \left. \frac{\partial Q_r}{\partial V_{B'C'}} \right|_{V_{B'E'}=cte} \quad C_{dC_be} = \left. \frac{\partial Q_r}{\partial V_{B'E'}} \right|_{V_{B'C'}=cte}$$

State of art

Method

Result

g_m & g_0 determination

$$\begin{bmatrix} g_{avl_c} + g_{avl_b} + 2\pi \cdot f_{req.} \cdot (C_{dE} + C_{dE_bc} + C_{dC_be} + C_{dC}) & -g_{avl_c} - j \cdot 2 \cdot \pi \cdot f_{req.} \cdot (C_{dE_bc} + C_{dC}) \\ g_m - g_{avl_c} - g_{avl_b} - j \cdot 2 \cdot \pi \cdot f_{req.} \cdot (C_{dC} + C_{dC_be}) & g_0 + g_{avl_c} + j \cdot 2 \cdot \pi \cdot f_{req.} \cdot C_{dC} \end{bmatrix}$$

$$g_m = R(Y_{21}) + R(Y_{11})$$

$$g_0 = R(Y_{22}) + R(Y_{12})$$

$R(Y_{11})$ and $R(Y_{12})$ are too noisy and sensitive to the deembedding and the measurement accuracy. In general $|g_m| \gg |g_{avl_b} + g_{avl_c}|$ and $|g_0| \gg |g_{avl_c}|$ then g_{avl_b} and g_{avl_c} could be neglected:

$$g_m \approx R(Y_{21})$$

$$g_0 \approx R(Y_{22})$$

N.B.: Another solution is to determine a self-consistent expression for g_0 and g_m using:

$$g_{avl_b} = -K_{avl.} \cdot (g_m + g_0)$$

$$g_{avl_c} = -K_{avl.} \cdot g_0 + g_a$$

State of art

Method

Result

C_{dC_be} negligible

$$\frac{\text{imag}(Y_{11})}{j.2.\pi.f_{\text{req}}} = C_{dE} + C_{dE_bc} + C_{dC} + C_{dC_be}$$

Rigorously $C_{dC_be} = \text{imag}(Y_{21})/(j.2.\pi.f_{\text{req}}) - \text{imag}(Y_{22})/(j.2.\pi.f_{\text{req}})$

However $\text{imag}(Y_{22})$ is too sensitive to the substrate network, moreover C_{dC_be} is low for $V_{BC} < 0.7V$, then practically C_{dC_be} is negligible.

$$\frac{\text{imag}(Y_{11})}{j.2.\pi.f_{\text{req}}} \approx C_{dE} + C_{dE_bc} + C_{dC}$$

State of art

Method

Result

T_F from $\text{Imag}(Y_{11})$

$$\frac{\text{imag}(Y_{11})}{j.2.\pi.f_{\text{req}}} \approx C_{dE} + C_{dE_bc} + C_{dC}$$

$$\left\{ \begin{array}{l} C_{dE} = \frac{\partial Q_F}{\partial v_{B'E'}} \Big|_{V_{B'C'}} + \frac{\partial I_{TF}}{\partial v_{B'E'}} \Big|_{V_{B'C'}} \cdot \frac{\partial Q_F}{\partial I_{TF}} \Big|_{V_{B'C'}} = \frac{\partial Q_{FF}}{\partial v_{B'E'}} \Big|_{V_{B'C'}} + (g_m + g_0).T_F \\ C_{dE_bc} = \frac{\partial Q_F}{\partial v_{B'C'}} \Big|_{V_{B'E'}} + \frac{\partial I_{TF}}{\partial v_{B'C'}} \Big|_{V_{B'E'}} \cdot \frac{\partial Q_f}{\partial I_{TF}} \Big|_{V_{B'E'}} = \left(I_{TF} \cdot \frac{dT_{f0}}{dv_{B'C'}} + \frac{\partial Q_{FF}}{\partial v_{B'C'}} \Big|_{V_{B'E'}} \right) - g_0.T_F \end{array} \right.$$

$$\frac{\partial Q_{FF}}{\partial v_{B'E'}} \Big|_{V_{B'C'}} = - \frac{\partial Q_{FF}}{\partial v_{B'C'}} \Big|_{V_{B'E'}} \quad \Rightarrow \quad \frac{\text{imag}(Y_{11})}{j.2.\pi.f_{\text{req}}} \approx g_m.T_F + I_{TF} \cdot \frac{dT_{f0}}{dv_{B'C'}} + C_{dC}$$

$$T_f \approx \frac{1}{g_m} \cdot \left(\frac{\text{imag}(Y_{11})}{j.2.\pi.f_{\text{req}}} - C_0 \right)$$

$$C_0 = I_{TF} \cdot \frac{dT_{f0}}{dv_{B'C'}} + C_{dC}$$

State of art

Method

Result

Determination of C_0 from $\text{Imag}(Y_{12})$ at low injection

$$-\frac{\text{imag}(Y_{12})}{j \cdot 2 \cdot \pi \cdot f_{\text{req}}} = C_{\text{dE_bc}} + C_{\text{dC}} = \left(\text{ITF} \cdot \frac{dT_{f0}}{dv_{B'C'}} + \frac{dQ_{FF}}{dv_{B'C'}} \Big|_{\substack{VB'E' \\ \text{ITF}}} \right) - g_0 \cdot T_F + C_{\text{dC}}$$

For the **low injection** region:

$$\frac{\partial Q_{FF}}{\partial v_{B'C'}} \Big|_{\substack{VB'E' \\ \text{ITF}}} \approx 0 \quad \text{and} \quad g_0 \cdot T_F \approx 0$$

Therefore:

$$-\frac{\text{imag}(Y_{12})}{j \cdot 2 \cdot \pi \cdot f_{\text{req}}} = C_{\text{dE_bc}} + C_{\text{dC}} \approx \text{ITF} \cdot \frac{dT_{f0}}{dv_{B'C'}} + C_{\text{dC}} = C_0$$

At **low injection** region (before the F_t peak):

$$C_0 \approx -\frac{\text{imag}(Y_{12})}{j \cdot 2 \cdot \pi \cdot f_{\text{req}}}$$

Determination of C_0 from $\text{Imag}(Y_{12})$ at high injection

At **low injection** and $V_{BC} < 0.4V$ $C_{dc} \approx 0$, then:

$$-\frac{\text{imag}(Y_{12})}{j \cdot 2 \cdot \pi \cdot f_{\text{req}}} \approx I_{TF} \cdot \frac{dT_{f0}}{dv_{B'C'}} + C_{dc} \approx I_{TF} \cdot \frac{dT_{f0}}{dv_{B'C'}}$$

$$-\frac{\text{imag}(Y_{12})}{j \cdot 2 \cdot \pi \cdot f_{\text{req}} \cdot I_{TF}} \approx \frac{dT_{f0}}{dv_{B'C'}} = D_{T0H} \cdot \frac{dc}{dv_{B'C'}} + T_{BVL} \cdot \frac{1}{C_{jci0}(T_j)} \cdot \frac{d(C_{jci}(T_j))}{dv_{B'C'}}$$

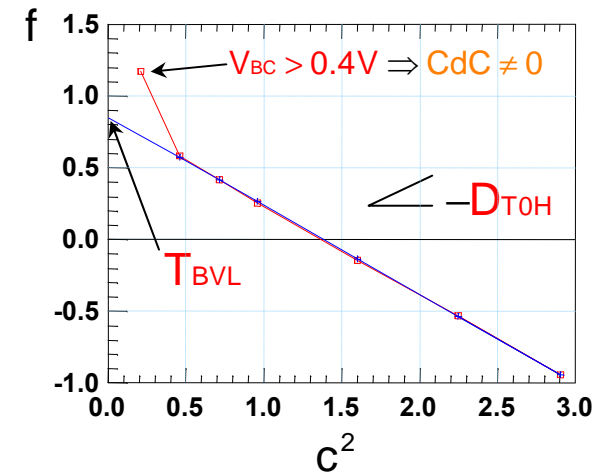
$$c = C_{jci0}(T_j) / C_{jci}(T_j)$$

$$T_{f0} = T_0 + D_{T0H} \cdot (c - 1) + T_{BVL} \cdot \left(\frac{1}{c} - 1 \right)$$

$$\frac{dc}{dv_{B'C'}} = -\frac{c^2}{C_{jci0}(T_j)} \cdot \frac{d(C_{jci}(T_j))}{dv_{B'C'}}$$

T_{BVL} and D_{T0H} are extracted from a linear regression:

$$f = \left(-\frac{\text{imag}(Y_{12})}{j \cdot 2 \cdot \pi \cdot f_{\text{req}} \cdot I_{TF}} \right) \cdot \frac{C_{jci0}(T_j)}{d(C_{jci}(T_j))} = T_{BVL} - c^2 \cdot D_{T0H}$$

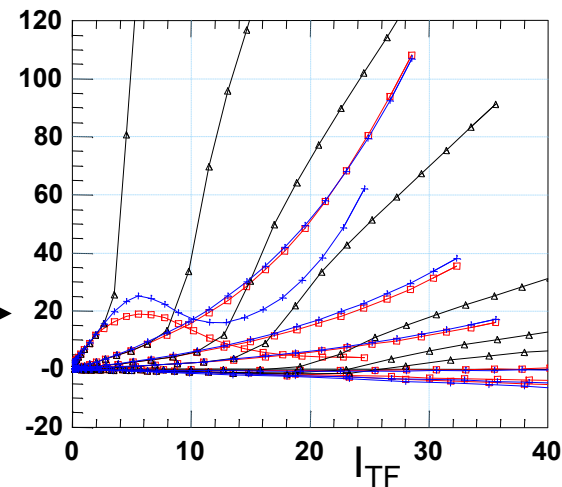
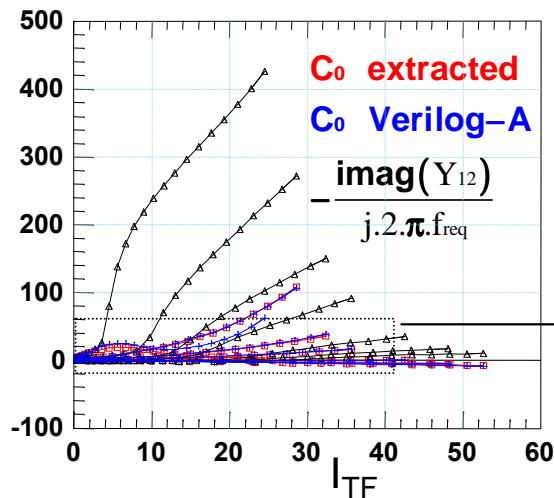


Determination of C_0 from $\text{Imag}(Y_{12})$ at high injection

For the **high injection** region (after the F_t peak):

$$C_0 = I_{TF} \cdot \left(D_{T0H} \cdot \frac{dc}{dv_{B'C'}} + T_{BVL} \cdot \frac{1}{C_{jci0}(T_j)} \cdot \frac{d(C_{jci}(T_j))}{dv_{B'C'}} \right) \Bigg|_{\text{calc}} + C_{dc}^*$$

$$C_{dc}^* = - \frac{\text{imag}(Y_{12})}{j \cdot 2 \cdot \pi \cdot f_{\text{req}}} \Bigg|_{\text{peak } F_t} - \left(I_{TF} \cdot \left(D_{T0H} \cdot \frac{dc}{dv_{B'C'}} + T_{BVL} \cdot \frac{1}{C_{jci0}(T_j)} \cdot \frac{d(C_{jci}(T_j))}{dv_{B'C'}} \right) \Bigg|_{\text{calc}} \right) \Bigg|_{\text{peak } F_t}$$



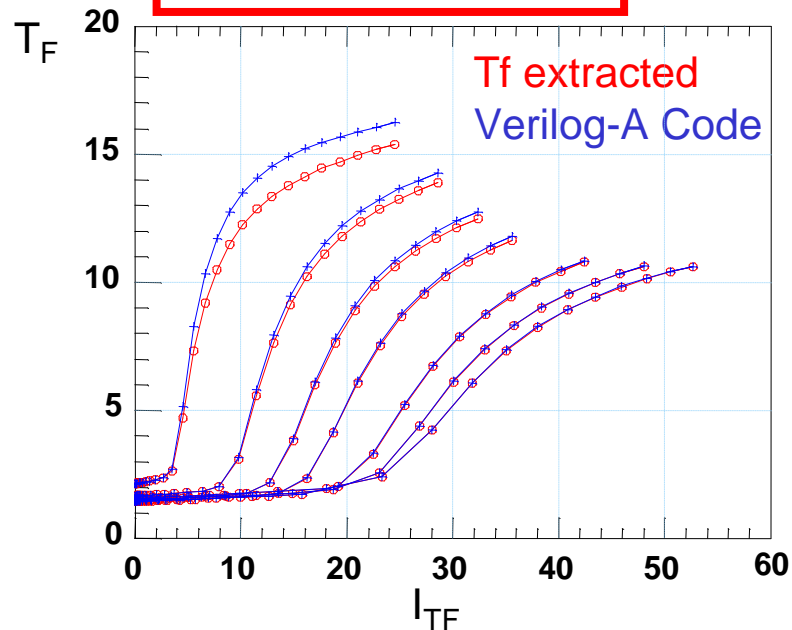
State of art

Method

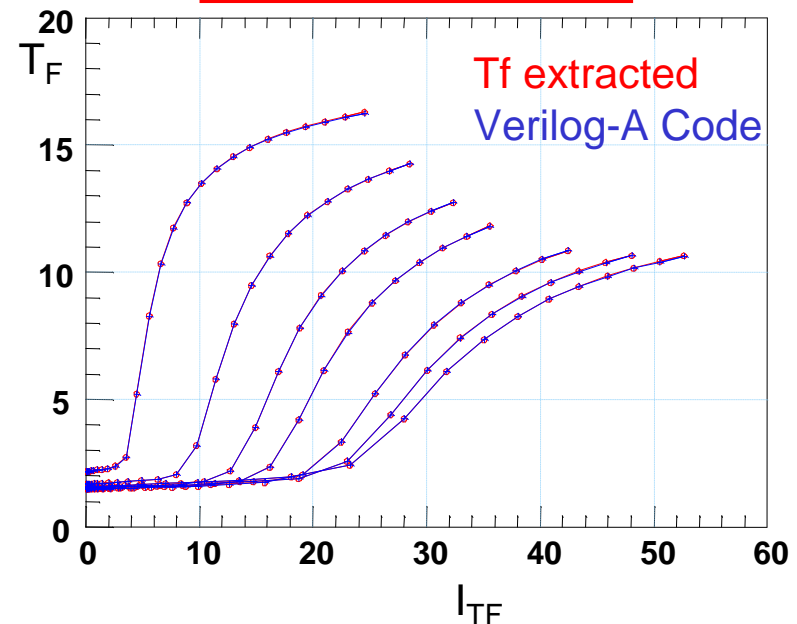
Result

Real improvement

$$T_f \approx \frac{\text{imag}(Y_{11} + Y_{12})}{j \cdot 2 \cdot \pi \cdot f_{\text{req}} \cdot g_m}$$



$$T_f \approx \frac{\text{imag}(Y_{11})}{j \cdot 2 \cdot \pi \cdot f_{\text{req}} \cdot g_m} - \frac{C_0}{g_m}$$



- ▶ Without C_0 the result is the same as the Malorny/Shröter and Huszka methods
- ▶ Full matrix deembedding convenient but actually not necessary
- ▶ Real improvement: T_{BVL} & D_{T0H} extraction and dT_{F0} calculation (C_0).



II – Extraction Results

State of art

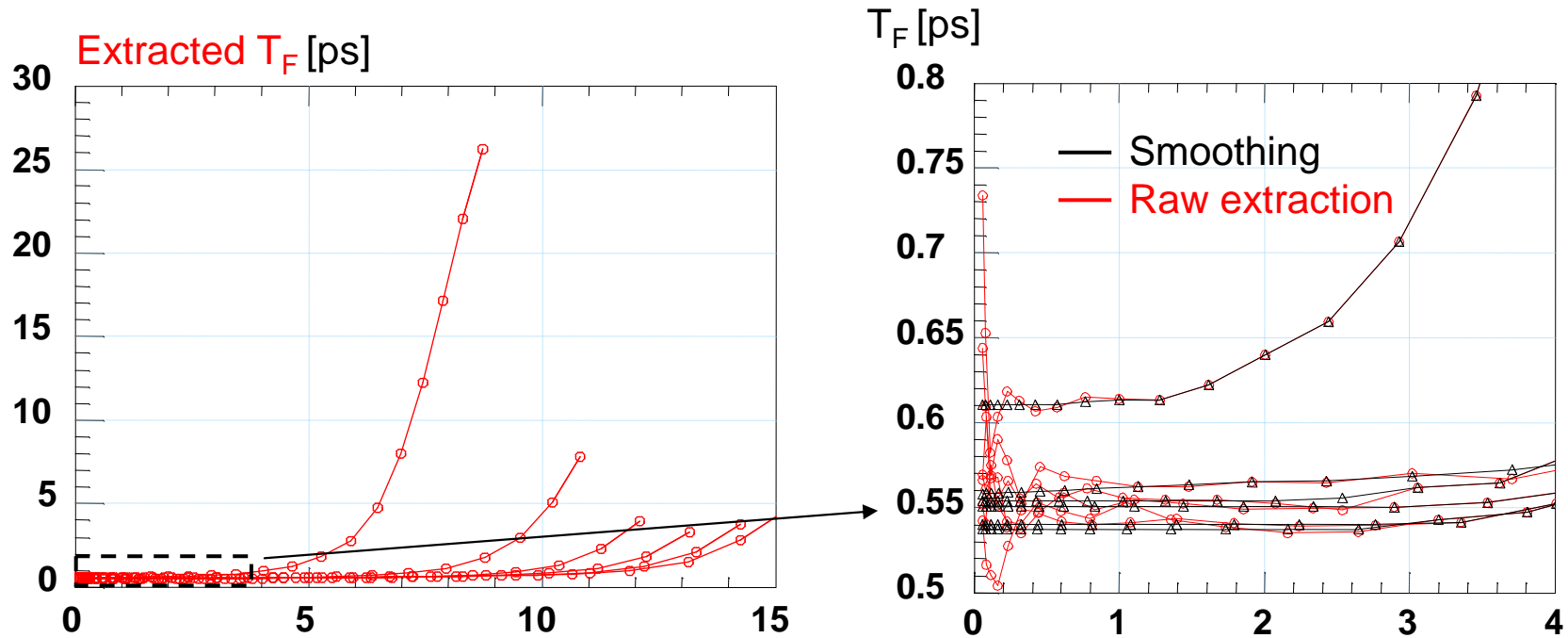
Method

Result

Application on measurement

BICMOS9 $W_E=0.3\mu\text{m}$, $L_E=3.70\mu\text{m}$

Final transit time extraction



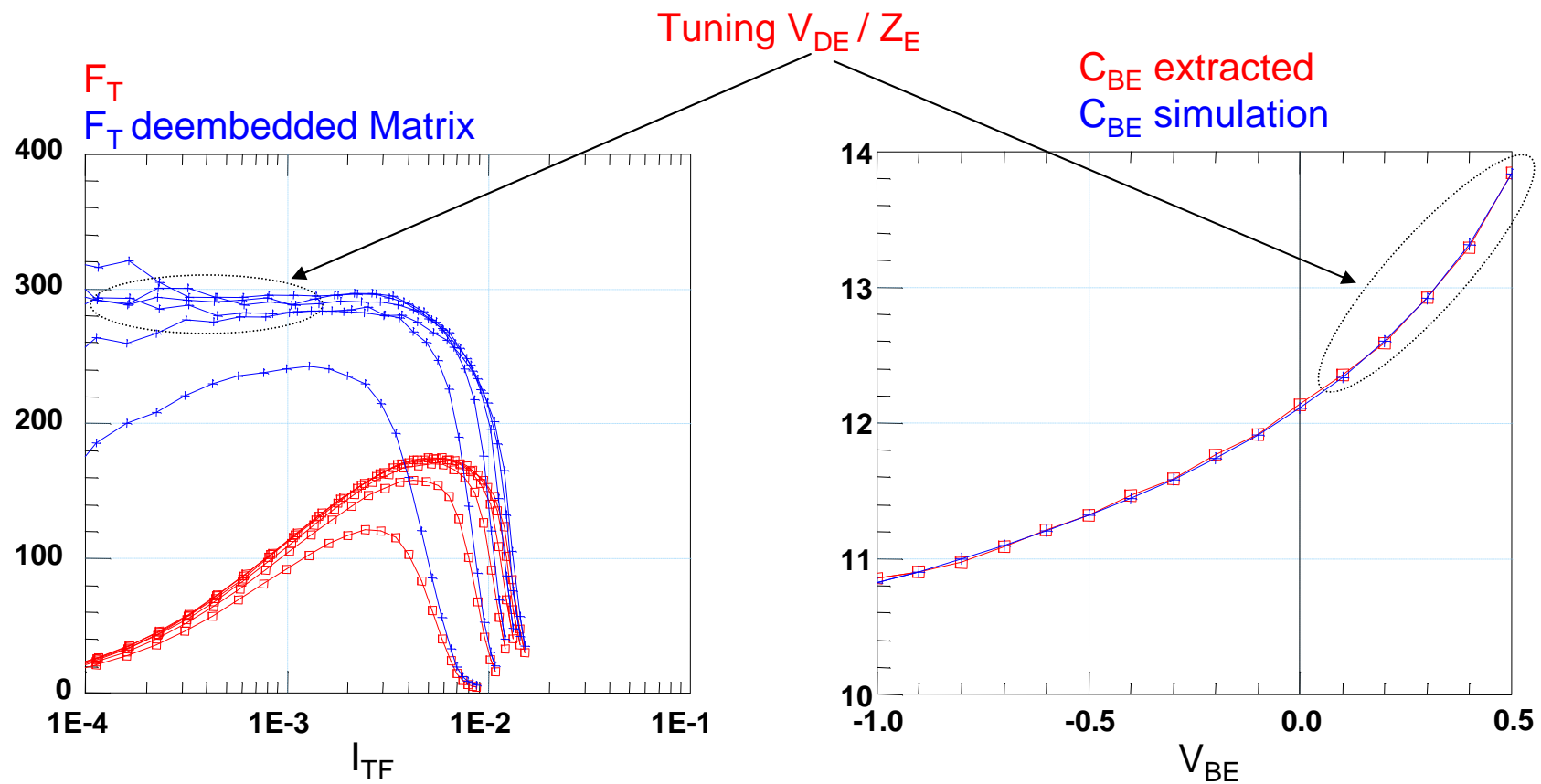
ST-BICMOS9 technology ($0.13\mu\text{m}$) : $F_T = 160 \text{ GHz}$, $F_{max} = 160 \text{ GHz}$

State of art	Method	Result
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Application on measurement

BICMOS9 $W_E=0.3\mu\text{m}$, $L_E=3.70\mu\text{m}$

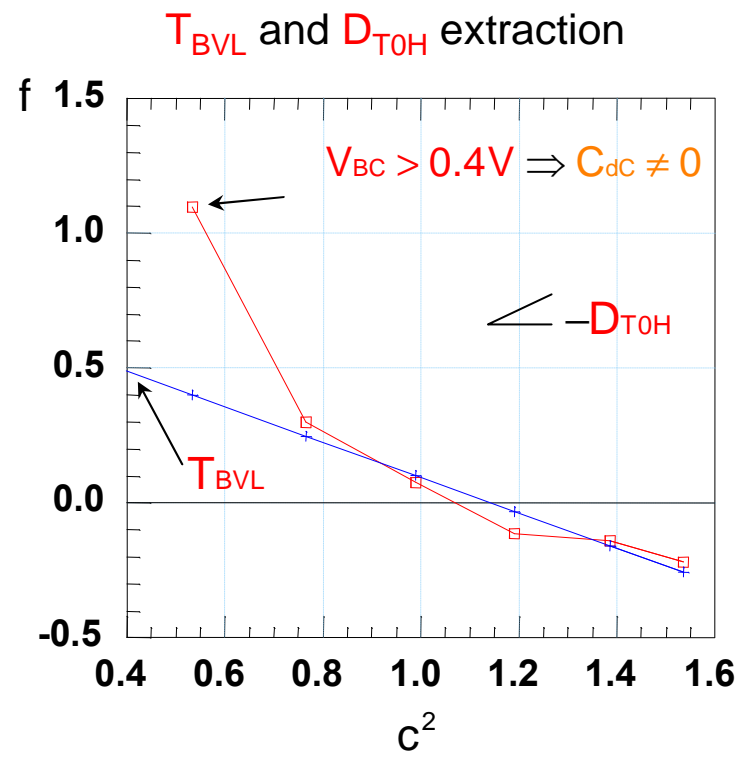
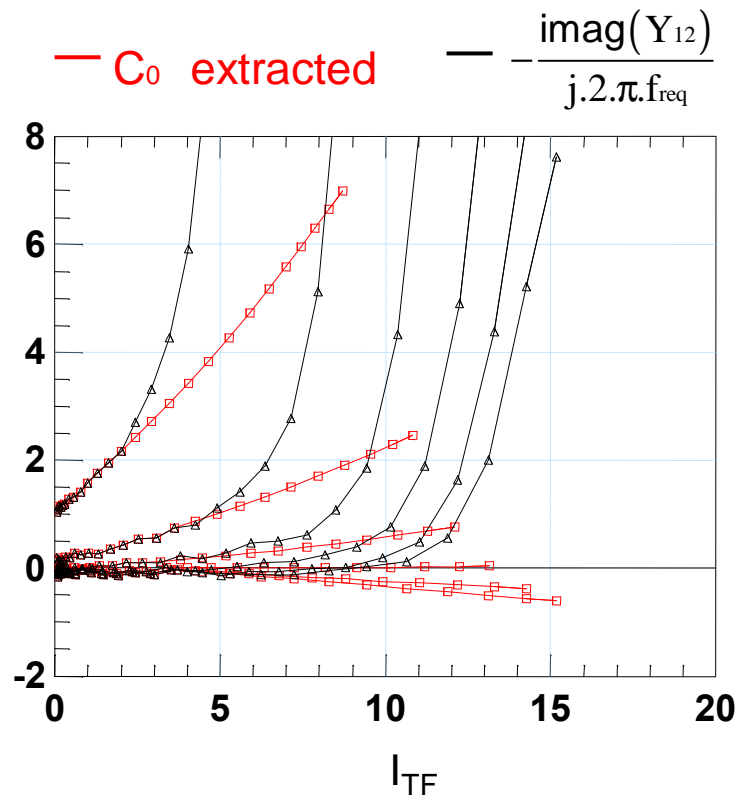
Base-emitter capacitance correction



State of art	Method	Result
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Application on measurement

BICMOS9 $W_E=0.3\mu\text{m}$, $L_E=3.70\mu\text{m}$



State of art	Method	Result
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Application on measurement

BICMOS9 $W_E=0.3\mu\text{m}$, $L_E=3.70\mu\text{m}$

Base-Collector capacitance correction

C_{BC} parameters **not** enough accurate for $V_{BC}>0$

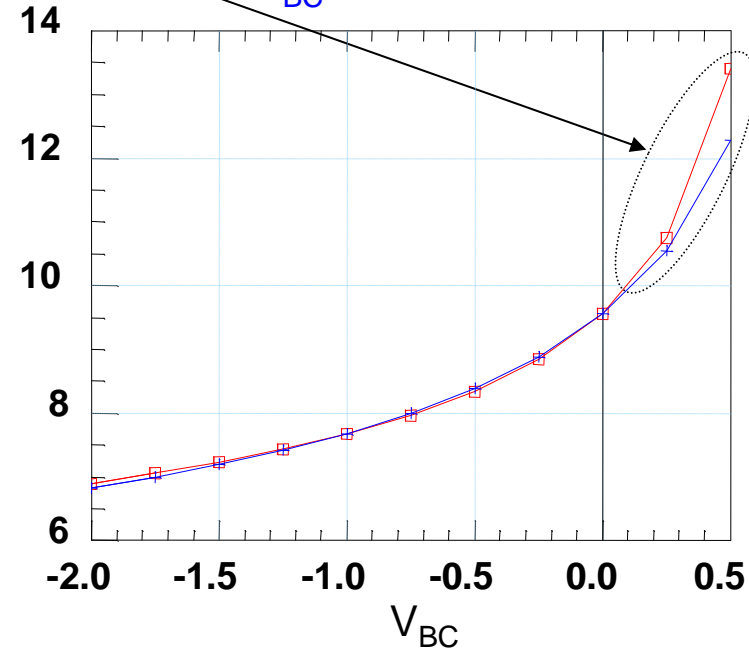
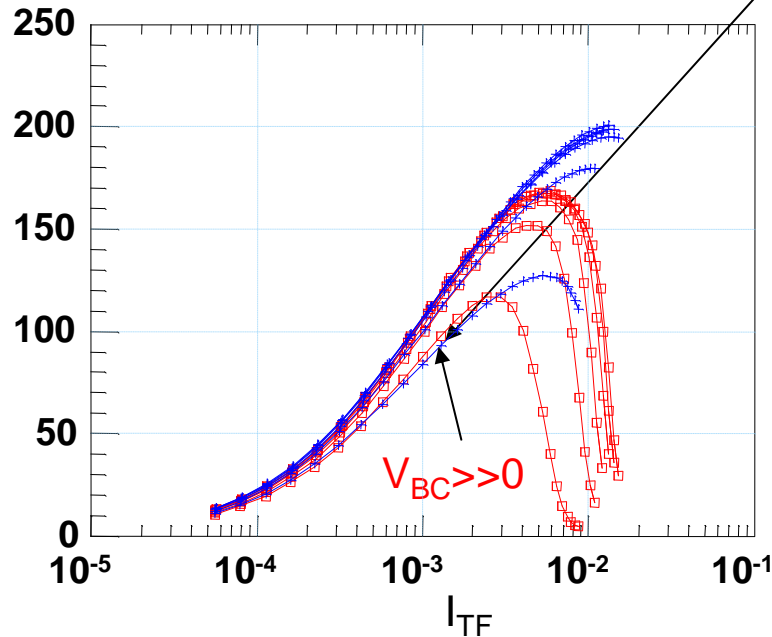
F_T measurement

F_T simulation

Tuning V_{DC}/Z_C

C_{BC} extracted

C_{BC} simulation



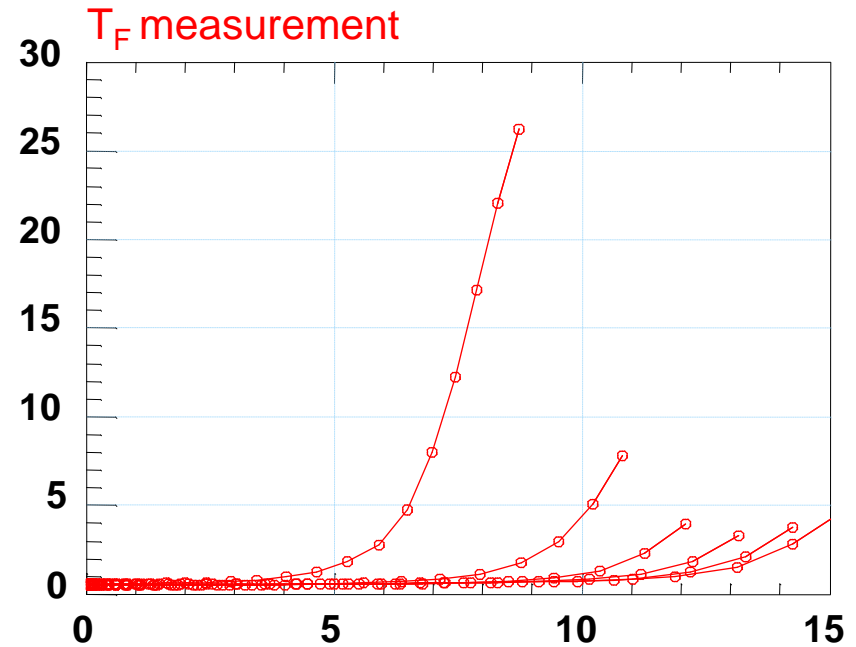
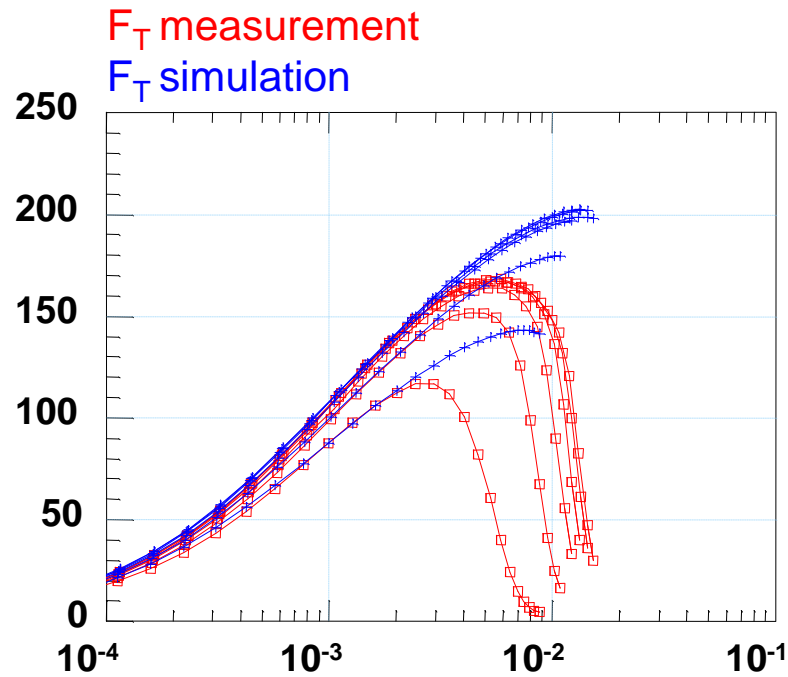
After direct T_{BVL} & D_{TOH} extraction

State of art	Method	Result
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Application on measurement

BICMOS9 $W_E=0.3\mu\text{m}$, $L_E=3.70\mu\text{m}$

Final transit time extraction



▣ IV – Conclusion

Conclusion

- ▶ **Highly accurate T_F extraction method including the saturation region**
 - Better approximation of T_F (better than $C_{dE} = g_m \cdot T_F$)
 - Full matrix deembedding convenient but not necessary
- ▶ **T_{BVL} & D_{TOH} extraction from Y_{12}**
 - Extraction using a linear regression
 - Method mainly sensitive to the well known C_{BC} capacitance only
- ▶ **Capacitance parameters optimization in forward mode**
 - FOM: deembedded F_T after matrix deembedding
 - Capacitance optimization without modifying the capacitance in reverse mode
- ▶ **New approach for r_{bi^*} extraction (Not presented):**
 - r_{bi^*} extraction less sensitive to the avalanche phenomenon