7 dot seven

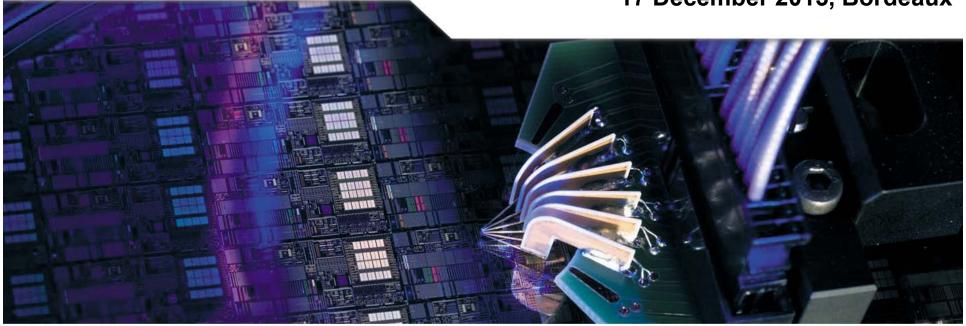
Safe Operating Limits of SiGe-THz Devices

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Dept. of Electrical Engg., IIT Madras

@University of Bordeaux during 2015

O15 SiGe-THz devices: Physics and reliability
17 December 2015, Bordeaux







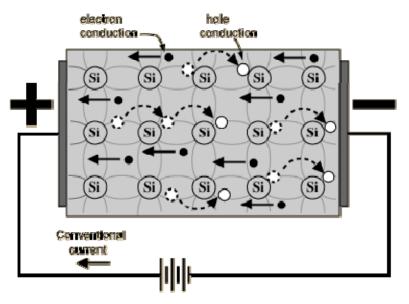


Outline

- Introduction
- Motivation
- Electro-Thermal (ET) Effects
- Impact Ionization (II) Effects
- Simultaneous ET and II Effects
- Device Design for Power Amplifier
- Multi-Finger Transistors
- Summary



Introduction



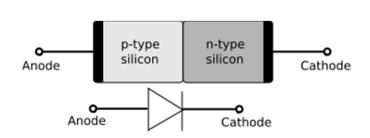
 Electrons and holes carry currents in a semiconductor material (Si, Ge, etc.)

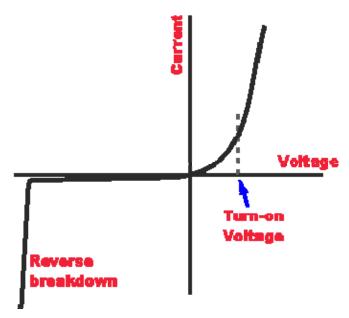
 Doping increases either electron density (n-type) or hole density (ptype)

 A huge conductivity range (~10⁻⁸ to 10³ S/cm) appears interesting for application devices



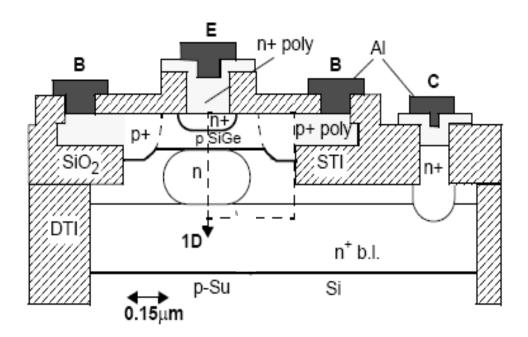
p-n diode







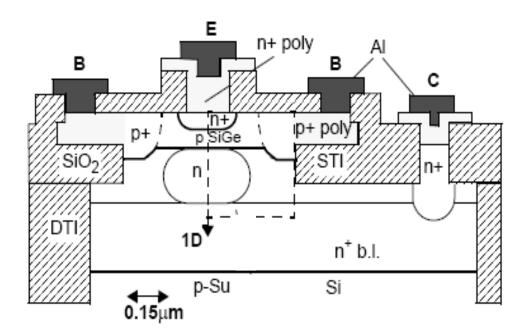
bipolar transistor

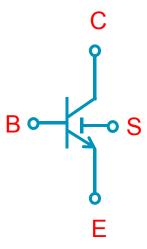






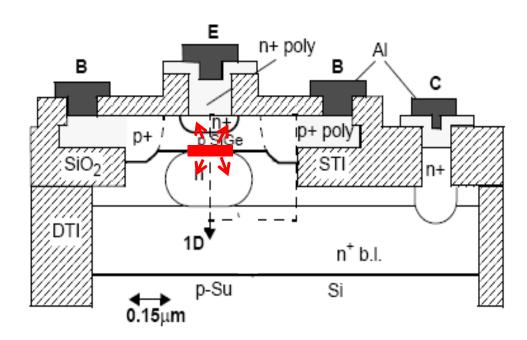
bipolar transistor

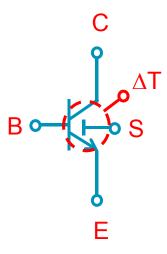






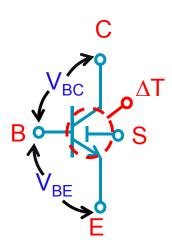
bipolar transistor



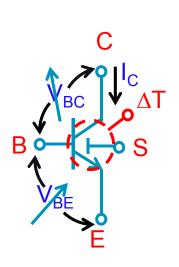


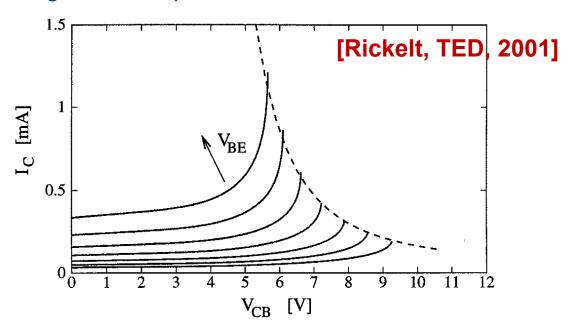
 $J \times E = I \times V / cm^3 = volume power density$



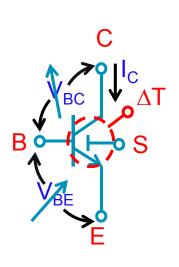


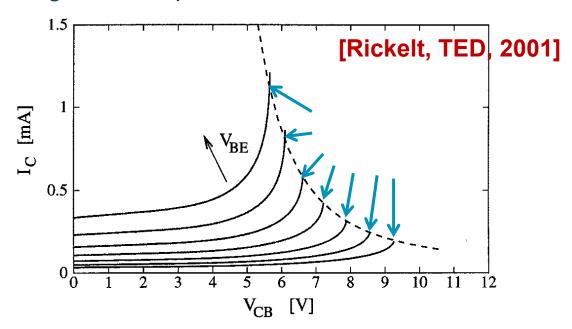




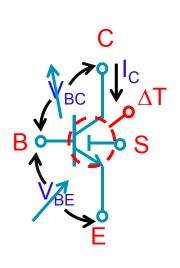


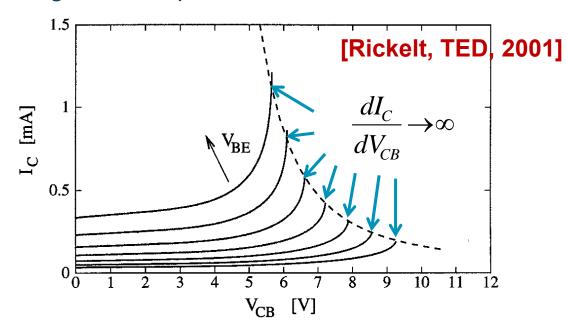






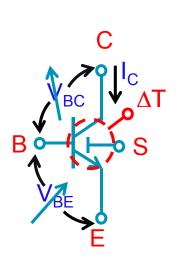


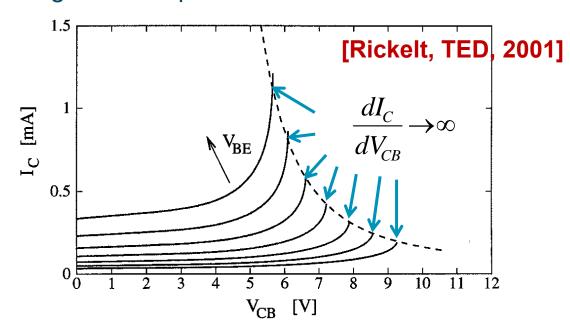






Safe operating limit of bipolar transistor



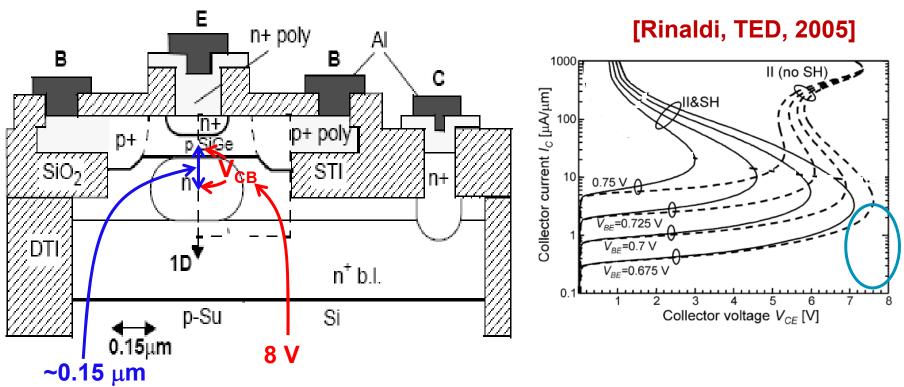


Two major factors

- Impact ionization (or avalanche breakdown)
- Electro-thermal heating (or self-heating)



Safe operating limit of bipolar transistor

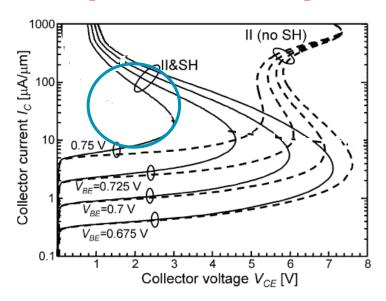


Electric field E~10⁶ V/cm → avalanche breakdown



Safe operating limit of bipolar transistor

[Rinaldi, TED, 2005]



high current density → high self-heating



Outline

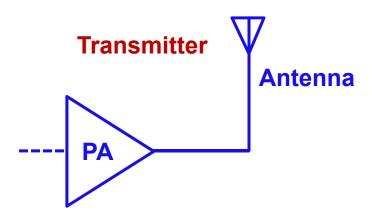
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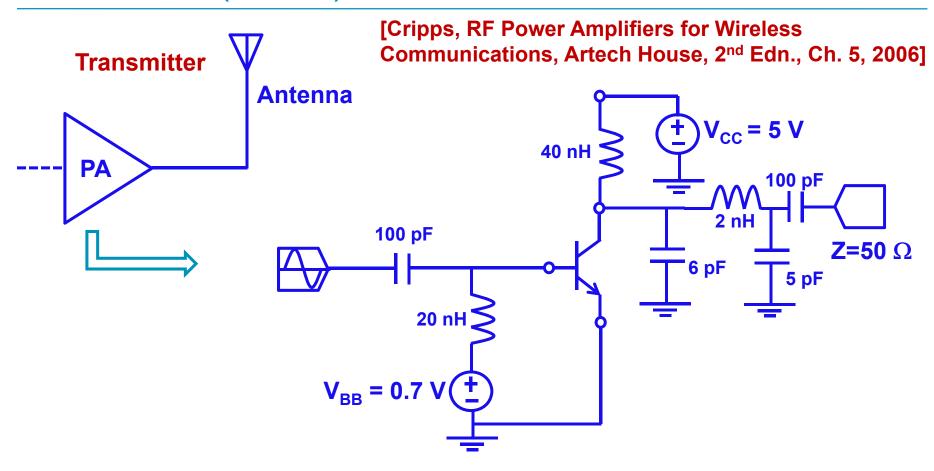
Motivation

- 1. Circuits that handle higher power, such as power amplifier (PA), usually forces the transistors to operate at their safe operating limits
- 2. While designing the PA, one should have clear idea on the safe operating limits of the given transistors
- 3. Transistors with higher safe operating limits are useful for PA design

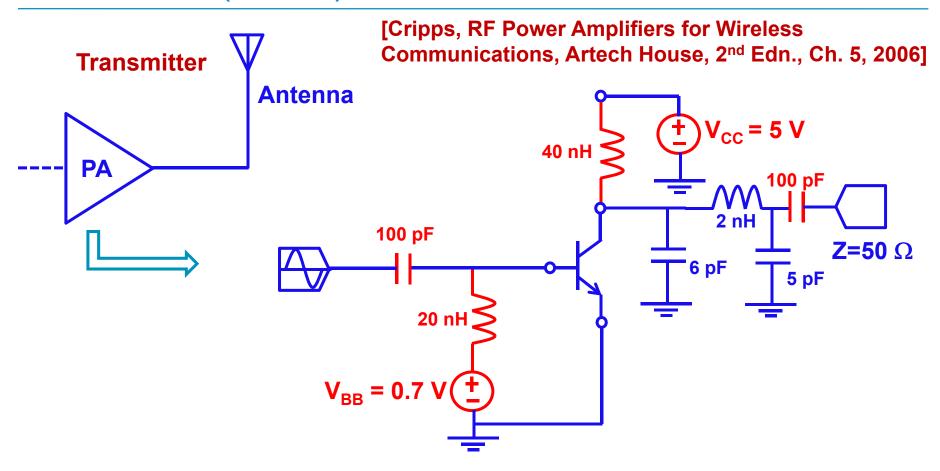




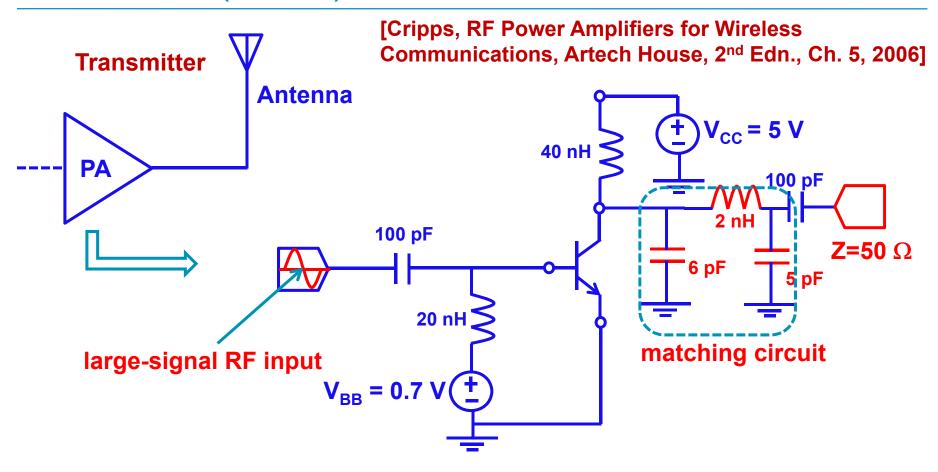




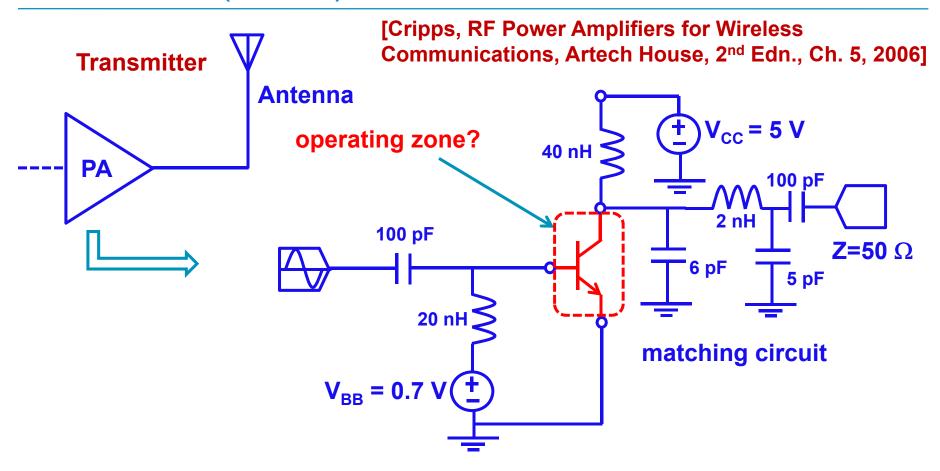




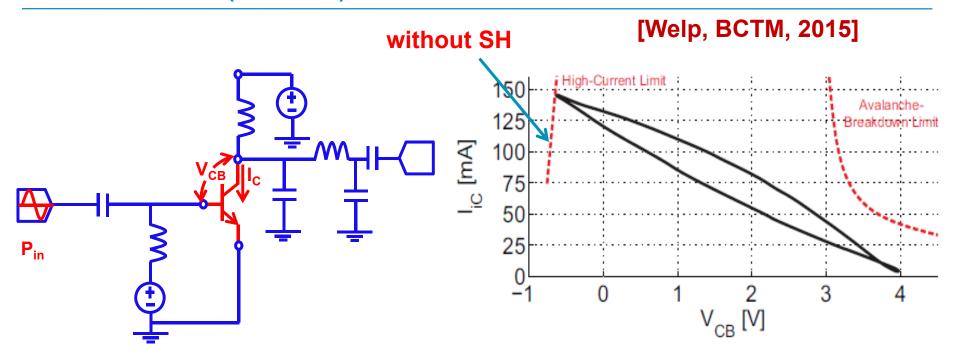




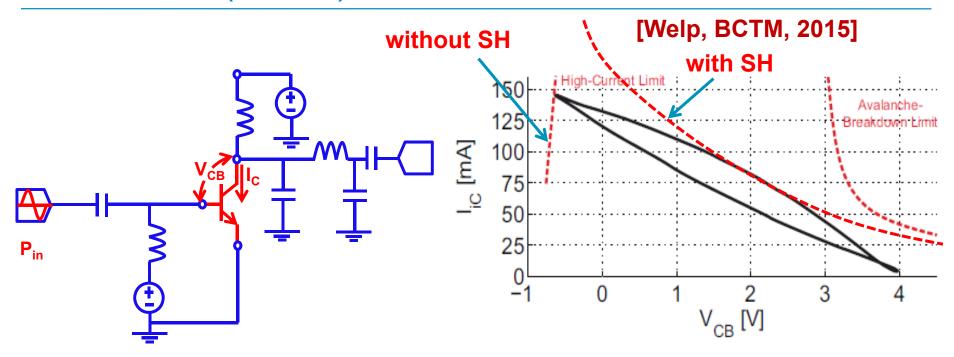












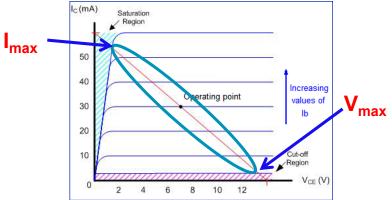
1. Circuits that handle higher power, such as power amplifier (PA), usually forces the transistors to operate at their safe operating limits



2. While designing the PA, one should have clear idea on the safe operating limits of the given transistors

PA design considerations (from transistor's perspective)

> To maximize the output power of the transistor, the optimal load value is equal to R_{opt} ≈ V_{max}/I_{max} which has to match with 50 Ω off-chip antenna



Usually I_{max} is high for bipolar transistors and the V_{max} is limited by the breakdown voltage that depends on bias configuration



3. Transistors with higher safe operating limits are useful for PA design

MOSFETs vs. Bipolar Transistors

- continued scaling aggressively reduces the BV for MOSFETs (more than BJTs)
- also I_{ON} for MOSFETs is saturated to ~1mA/μm in the newer technology nodes
- ➤ larger bias current needed to obtain a comparable output power → requires larger MOSFETs
- R_{opt}=BV/I_{max}=BV/2.I_{dc} appears smaller → complicated output matching
- ➤ relatively larger BV of BJTs permits lower bias current → smaller devices.
- simplified output matching!!
- design better bipolar transistors for high end PAs



Understanding the theory behind the safe operating limits of modern bipolar transistors is important!!

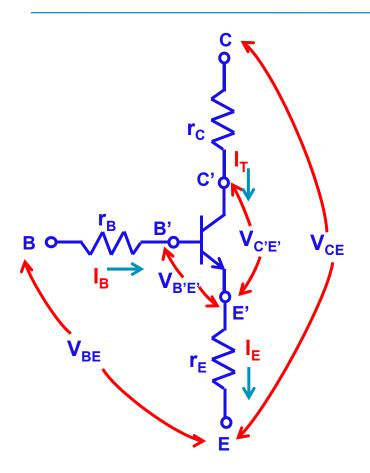
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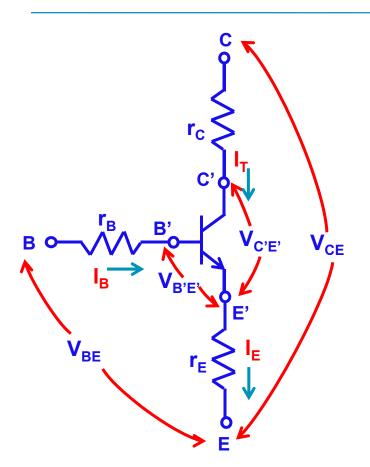
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Electrical current dissipates power within the device increasing the junction temperature, which in turn increases the electrical current further, and so on and so forth.....a positive feedback...causing an instability or unsafe operation.



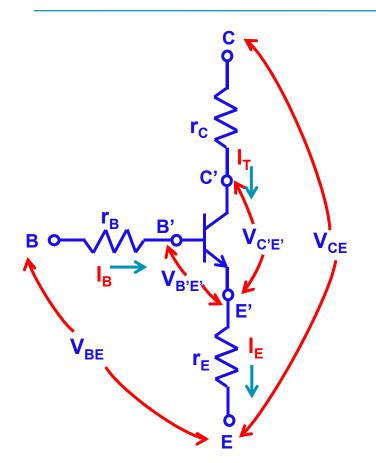
$$I_C = I_T = \frac{I_S}{1 - \frac{V_{CE}}{V_A}} \exp\left(\frac{V_{B'E'} + \phi \Delta T}{\eta V_{T0}}\right)$$

$$V_{B'E'} = V_{BE} - I_B r_B - I_E r_E = V_{BE} - I_C R_{EB}$$

$$\Delta T = R_{TH} P_{diss} = R_{TH} (I_B V_{BE} + I_C V_{CE}) = R_{TH} I_C V_{eq}$$

$$V_{eq} = V_{CE} + V_{BE} \left(\frac{1}{\alpha_F} - 1 \right)$$

$$R_{EB} = \frac{R_E}{\alpha_F} + \frac{R_B}{\beta_F} \qquad \phi = -\frac{\partial V_{BE}}{\partial T} \bigg|_{I_C}$$

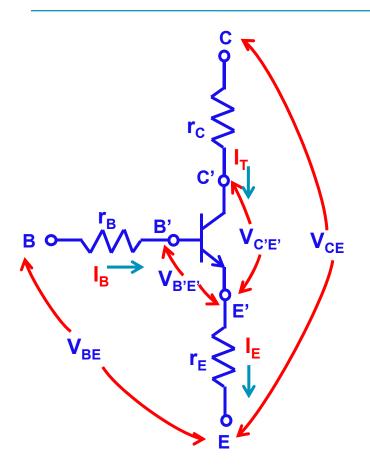


$$I_{C} = I_{T} = \frac{I_{S}}{1 - \frac{V_{CE}}{V_{A}}} \exp\left(\frac{V_{B'E'} + \phi \Delta T}{\eta V_{T0}}\right)$$

$$V_{B'E'} = V_{BE} - I_{B}r_{B} - I_{E}r_{E} = V_{BE} - I_{C}R_{EB}$$

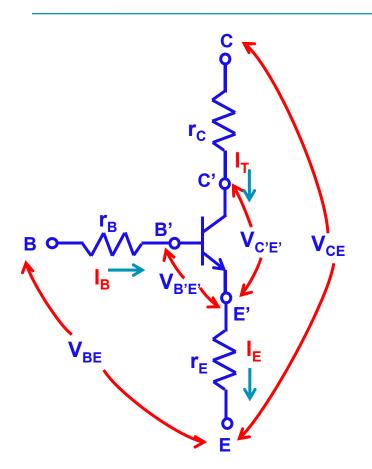
$$\Delta T = R_{TH}P_{diss} = R_{TH}(I_{B}V_{BE} + I_{C}V_{CE}) = R_{TH}I_{C}V_{eq}$$

$$\begin{aligned} V_{eq} &= V_{CE} + V_{BE} \left(\frac{1}{\alpha_F} - 1 \right) \\ R_{EB} &= \frac{R_E}{\alpha_F} + \frac{R_B}{\beta_F} \qquad \qquad \phi = -\frac{\partial V_{BE}}{\partial T} \bigg|_{I_C} \end{aligned}$$



$$I_{C} = I_{T} = \frac{I_{S}}{1 - \frac{V_{CE}}{V_{A}}} \exp\left(\frac{V_{BE} + I_{C} \left[\phi R_{TH} V_{eq} - R_{EB}\right]}{\eta V_{T0}}\right)$$

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$$I_{C} = I_{T} = \frac{I_{S}}{1 - \frac{V_{CE}}{V_{A}}} \exp\left(\frac{V_{BE} + I_{C} \left[\phi R_{TH} V_{eq} - R_{EB}\right]}{\eta V_{T0}}\right)$$

$$V_{eq} = V_{CE} + V_{BE} \left(\frac{1}{\alpha_F} - 1 \right) V_{CE}$$

$$R_{EB} = \frac{R_E}{\alpha_F} + \frac{R_B}{\beta_F}$$

$$\phi = -\frac{\partial V_{BE}}{\partial T}\Big|_{I_{a}}$$



$$I_{C} = \frac{I_{S}}{1 - \frac{V_{CE}}{V_{A}}} \exp\left(\frac{V_{BE} + I_{C} \left[\phi R_{TH} V_{CE} - R_{EB}\right]}{\eta V_{T0}}\right)$$



$$I_{C} = \frac{I_{S}}{1 - \frac{V_{CE}}{V_{A}}} \exp\left(\frac{V_{BE} + I_{C}[\phi R_{TH}V_{CE} - R_{EB}]}{\eta V_{T0}}\right)$$

$$V_{CE} \to 0$$

$$I_C = I_{C0} = I_S \exp\left(\frac{V_{BE} - R_{EB}I_C}{\eta V_{T0}}\right)$$



$$I_{C} = \frac{I_{S}}{1 - \frac{V_{CE}}{V_{A}}} \exp \left(\frac{V_{BE} + I_{C} [\phi R_{TH} V_{CE} - R_{EB}]}{\eta V_{T0}} \right)$$

$$V_{CE} \rightarrow 0$$

$$I_{C0} = I_{S} \exp\left(\frac{V_{BE} - R_{EB}I_{C}}{\eta V_{T0}}\right) \qquad r_{EB} = \frac{R_{EB}I_{C0}}{V_{T0}} \qquad v_{A} = \frac{\phi R_{TH}V_{A}I_{C0}}{V_{T0}}$$

$$i = \frac{I_C}{I_{C0}}$$

$$v = \frac{\phi R_{TH} V_{CE} I_{C0}}{V_{T0}}$$

$$r_{EB} = \frac{R_{EB}I_{C0}}{V_{T0}}$$

$$v_A = \frac{\phi R_{TH} V_A I_{C0}}{V_{T0}}$$



$$i = \frac{\exp((v - r_{EB})i + r_{EB})}{1 - \frac{v}{v_A}}$$

$$i = \frac{I_C}{I_{C0}}$$

$$v = \frac{\phi R_{TH} V_{CE} I_{C0}}{V_{T0}}$$

$$r_{EB} = \frac{R_{EB}I_{C0}}{V_{T0}}$$

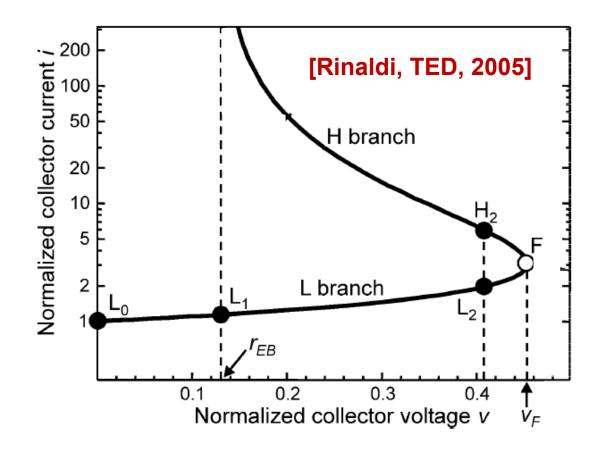
$$v_A = \frac{\phi R_{TH} V_A I_{C0}}{V_{T0}}$$



Iterative solution

$$i = \frac{\exp((v - r_{EB})i + r_{EB})}{1 - \frac{v}{v_A}}$$

$$r_{EB} = 0.13$$
$$v_A \to \infty$$

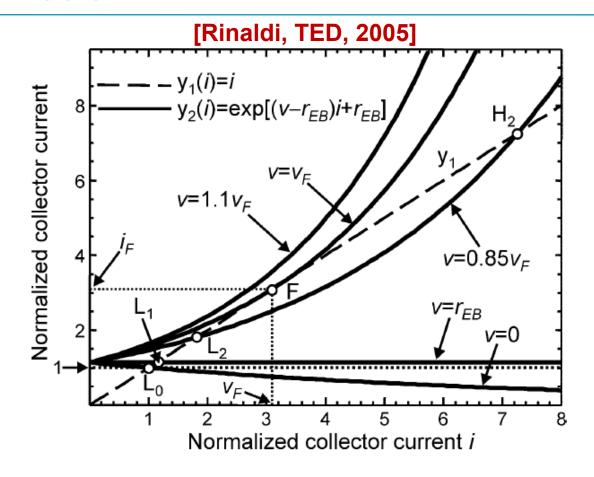




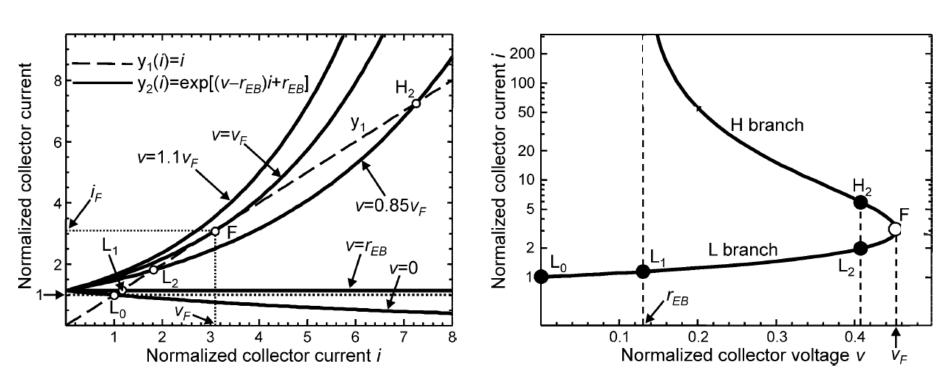
Geometric solution

$$i = \frac{\exp((v - r_{EB})i + r_{EB})}{1 - \frac{v}{v_A}}$$

$$r_{EB} = 0.13$$
$$v_A \to \infty$$

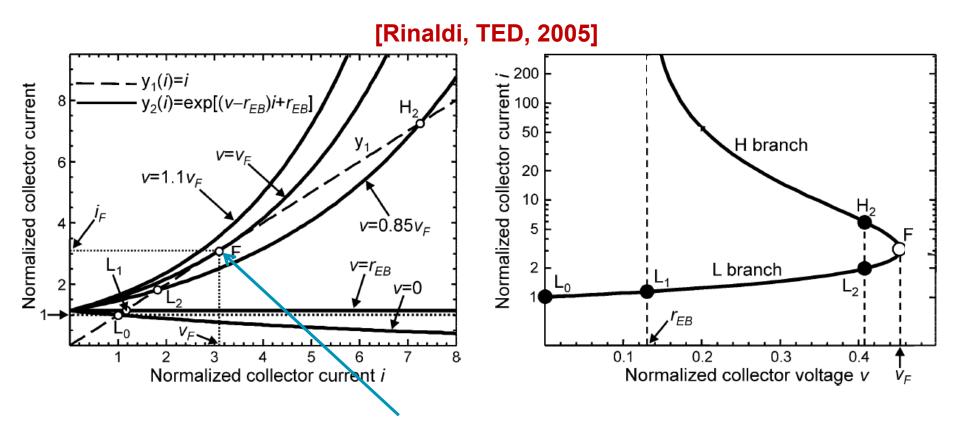






[Rinaldi, TED, 2005]





y₁(i) and y₂(i) are tangent at this flyback point



Therefore, the flyback locus can be obtained by differentiating

$$i = \frac{\exp((v - r_{EB})i + r_{EB})}{1 - \frac{v}{v_A}}$$

that gives

$$i = \frac{1}{v - r_{EB}}$$



Therefore, the flyback locus can be obtained by differentiating

$$i = \frac{\exp((v - r_{EB})i + r_{EB})}{1 - \frac{v}{v_A}}$$

that gives

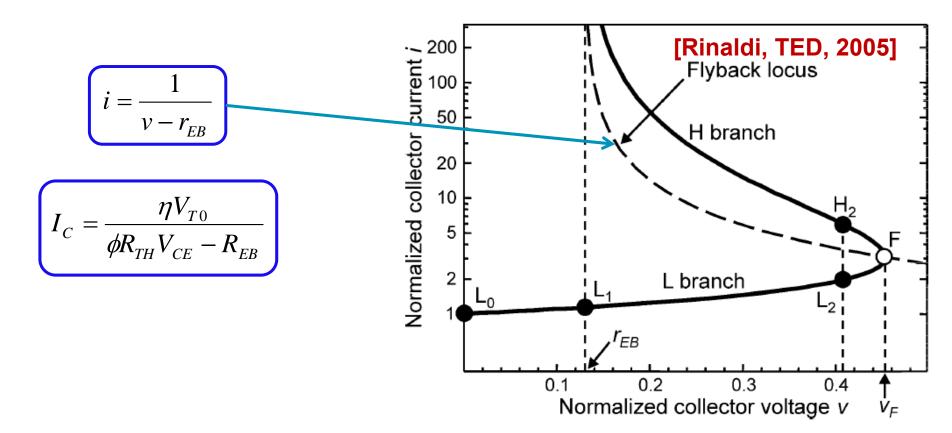
$$i = \frac{1}{v - r_{EB}}$$

Solving above two equations, we get flyback current and voltage

$$i_F = \frac{\exp(1 + r_{EB}) + \frac{1}{v_A}}{1 - \frac{r_{EB}}{v_A}}$$

$$v_{F} = \frac{\frac{1}{\exp(1 + r_{EB})} + r_{EB}}{1 + \frac{1}{v_{A} \exp(1 + r_{EB})}}$$

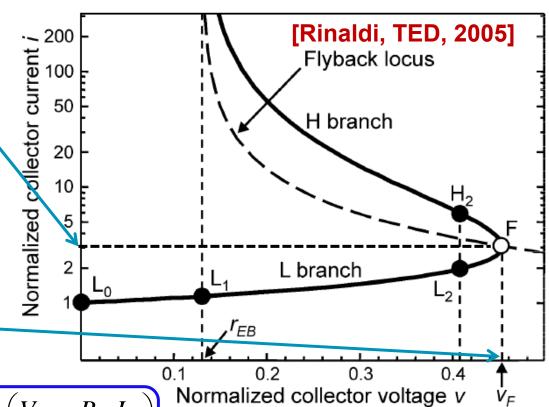




This flyback locus determines the safe operating limits of the transistor

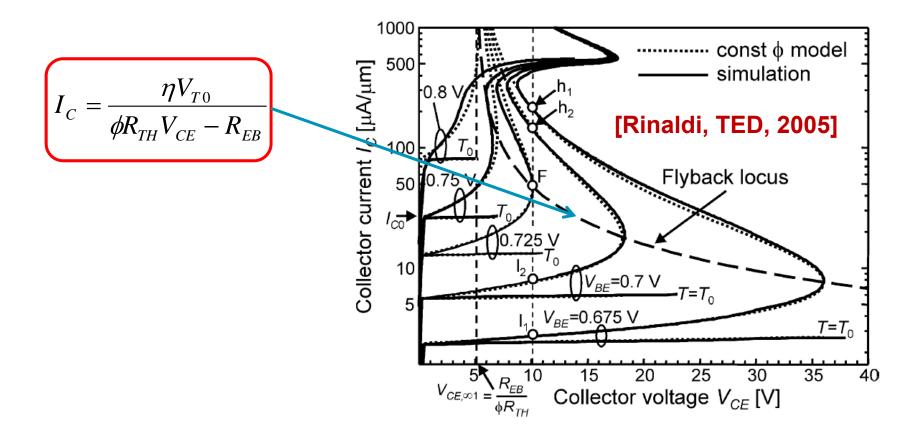
$$i_{F} = \frac{\exp(1 + r_{EB}) + \frac{1}{v_{A}}}{1 - \frac{r_{EB}}{v_{A}}}$$

$$v_{F} = \frac{\frac{1}{\exp(1 + r_{EB})} + r_{EB}}{1 + \frac{1}{v_{A} \exp(1 + r_{EB})}}$$



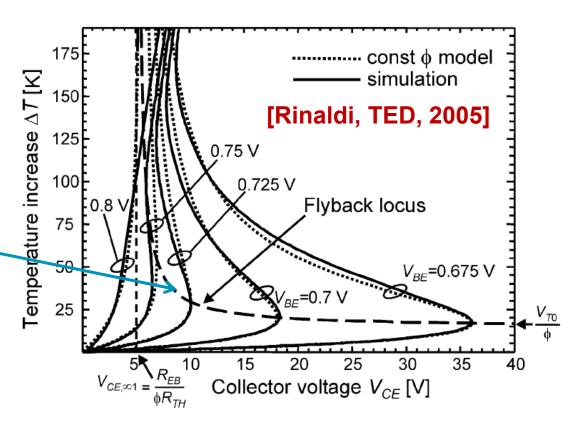
Normalizing current

$$I_{C0} = I_S \exp \left(\frac{V_{BE} - R_{EB}I_C}{\eta V_{T0}} \right)$$





$$\Delta T = R_{TH} V_{CE} I_C = rac{R_{TH} V_{CE} \eta V_{T0}}{\phi R_{TH} V_{CE} - R_{EB}}$$

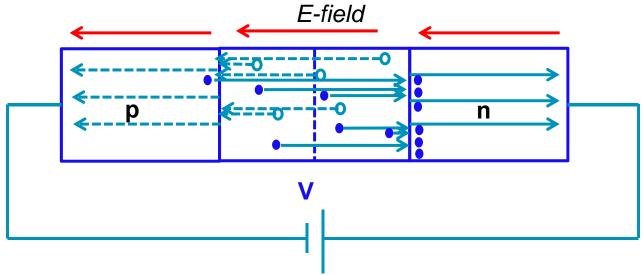




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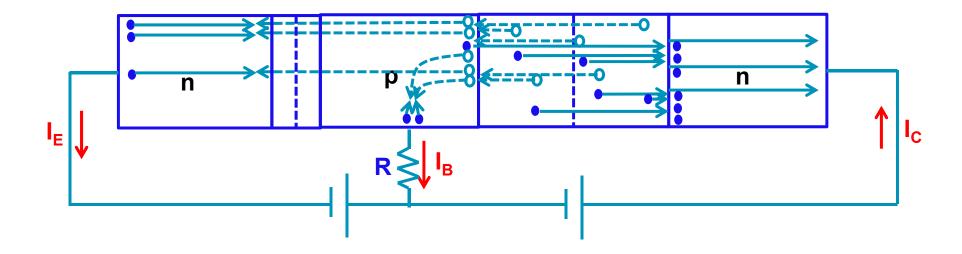
- > Avalanche of carrier generation
- > Holes move toward p-side
- > Electrons move toward n-side

Multiplication factor

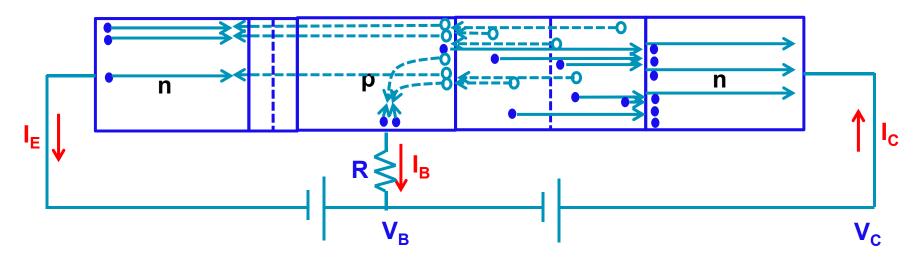
$$M = \frac{I_{out}}{I_{in}} = \frac{1}{1 - \left(\frac{V}{BV}\right)^m}$$

Breakdown voltage







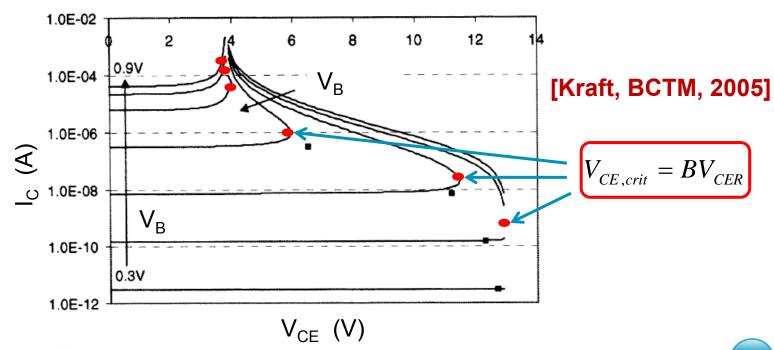


$$I_C = MI_S \exp\left(\frac{V_B + RI_C(M-1)/M - 1/\beta_F}{V_{T0}}\right)$$

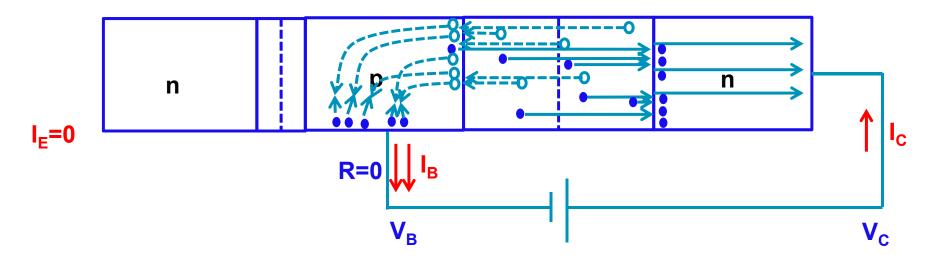
$$M = \frac{1}{1 - \left(\frac{V_{CB}}{BV_{CB0}}\right)^m}$$

$$I_C = MI_S \exp\left(\frac{V_B + RI_C(M-1)/M - 1/\beta_F}{V_{T0}}\right)$$

$$M = \frac{1}{1 - \left(\frac{V_{CB}}{BV_{CB0}}\right)^m}$$







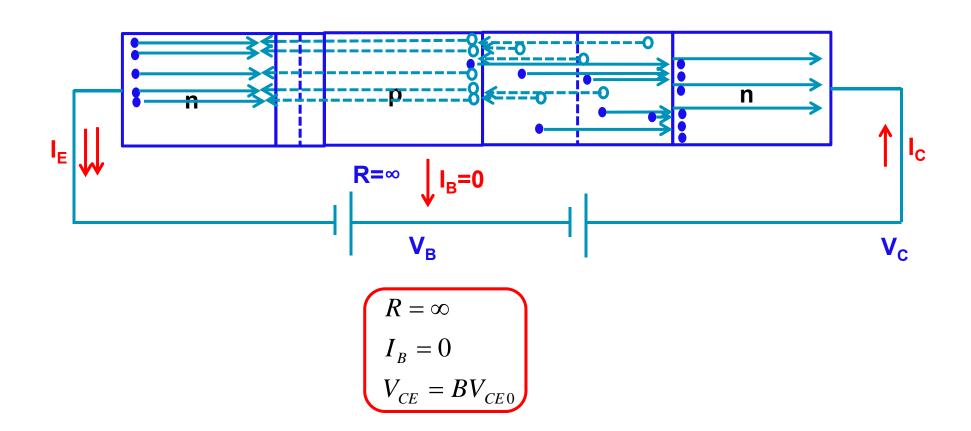
$$M = \frac{1}{1 - \left(\frac{V_{CB}}{BV_{CB0}}\right)^m}$$

$$R = 0$$

$$M \to \infty$$

$$V_{CB} = BV_{CB0}$$

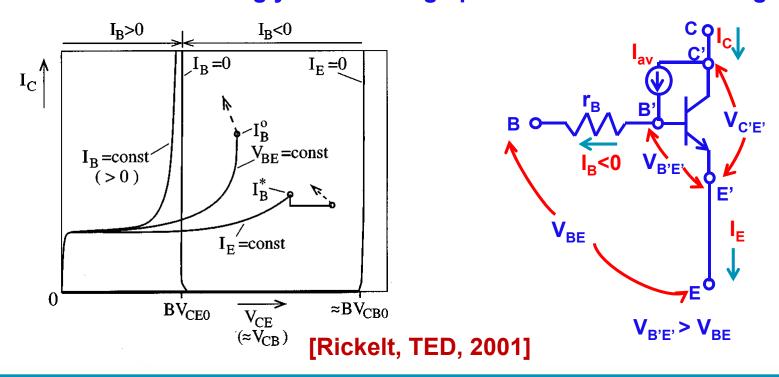




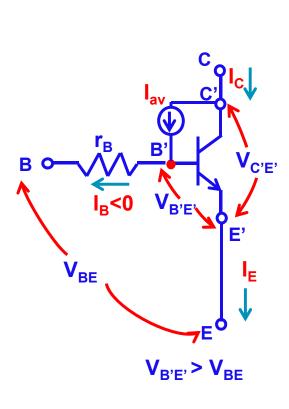


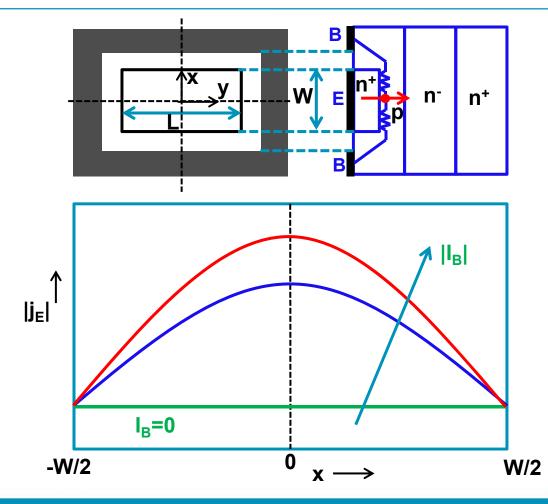
$$BV_{CB0} > BV_{CER} > BV_{CE0}$$

One can bias accordingly to obtain high possible breakdown voltage





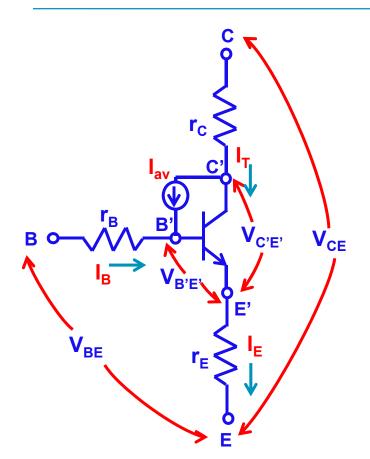






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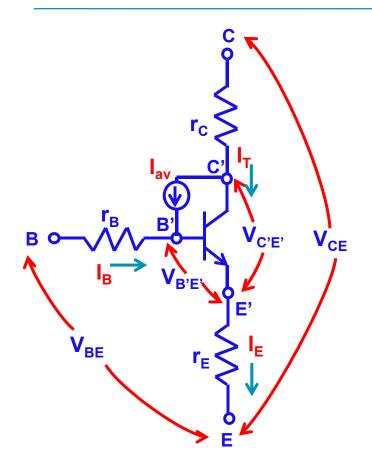
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$$V_{B'E'} = V_{BE} - I_{B} r_{B} - I_{E} r_{E} = V_{BE} - I_{C} R_{eq}$$

$$\Delta T = R_{TH}P_{diss} = R_{TH}(I_BV_{BE} + I_CV_{CE}) = R_{TH}I_CV_{eq}$$

$$V_{eq} = V_{CE} + V_{BE} \left(\frac{1}{\alpha_F} - 1 \right) \qquad \phi = -\frac{\partial V_{BE}}{\partial T} \bigg|_{I_C}$$

$$R_{eq} = \frac{R_E}{\alpha_F} + \frac{R_B}{\beta_F} - \frac{R_B + R_E}{\alpha_F} \left(1 - \frac{1}{M} \right) = \frac{R_B + R_E}{M\alpha_F} - R_B$$

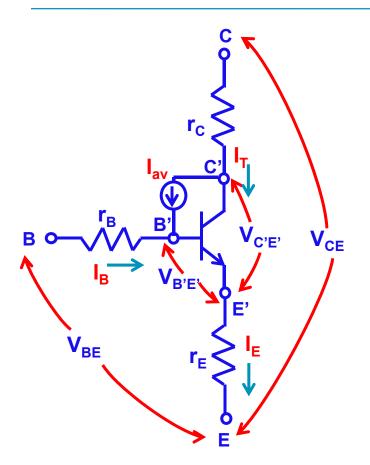


$$I_{C} = MI_{T} = \frac{MI_{S}}{1 - \frac{V_{CE}}{V_{A}}} \exp\left(\frac{V_{B'E'} + \phi \Delta T_{CE}}{\eta V_{T0}}\right)$$

$$V_{B'E'} = V_{BE} - I_{B}r_{B} - I_{E}r_{E} = V_{BE} - I_{C}R_{eq}$$

$$\Delta T = R_{TH}P_{diss} = R_{TH}(I_{B}V_{BE} + I_{C}V_{CE}) = (R_{TH}I_{C}V_{eq})$$

$$\begin{aligned} V_{eq} &= V_{CE} + V_{BE} \left(\frac{1}{\alpha_F} - 1 \right) & \phi &= -\frac{\partial V_{BE}}{\partial T} \Big|_{I_C} \\ R_{eq} &= \frac{R_E}{\alpha_F} + \frac{R_B}{\beta_F} - \frac{R_B + R_E}{\alpha_F} \left(1 - \frac{1}{M} \right) = \frac{R_B + R_E}{M\alpha_F} - R_B \end{aligned}$$



$$I_{C} = \frac{MI_{S}}{1 - \frac{V_{CE}}{V_{A}}} \exp\left(\frac{V_{BE} + I_{C} \left[\phi R_{TH} V_{eq} - R_{eq}\right]}{\eta V_{T0}}\right)$$

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The flyback locus can be obtained by differentiating

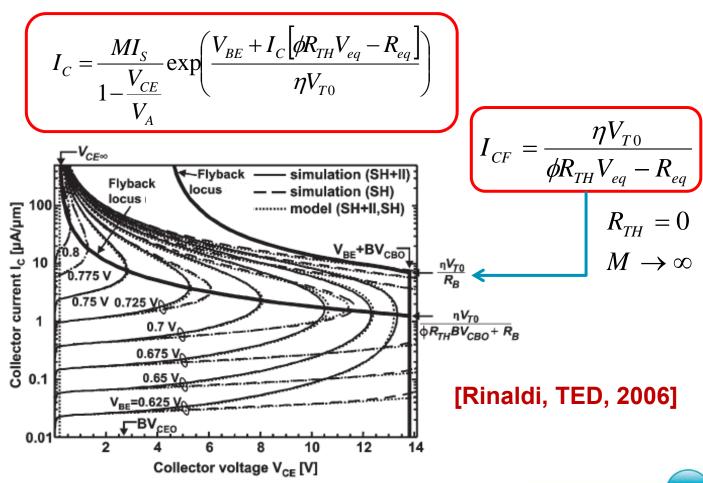
$$I_C = \frac{MI_S}{1 - \frac{V_{CE}}{V_A}} \exp\left(\frac{V_{BE} + I_C \left[\phi R_{TH} V_{eq} - R_{eq}\right]}{\eta V_{T0}}\right)$$
 w.r.t. V_{CE}

and putting

$$\frac{dI_C}{dV_{CE}} \to \infty$$

that gives

$$I_{CF} = \frac{\eta V_{T0}}{\phi R_{TH} V_{eq} - R_{eq}}$$





Outline

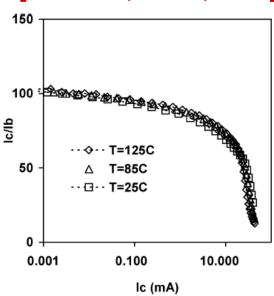
- Introduction
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Why SiGe HBT? Why not GaAs HBT?

- ✓ Reduced chip area and increased chip robustness due to heat-conductive Si substrate
- ✓ Temperature insensitive current gain reduces the circuit design issues arising from thermal runaway
- ✓ Reliabilities at high current densities enables further reduction in device size

[Johnson, JSSC, 2004]





- ✓ BV_{CB0} and BV_{CER} are more important than BV_{CE0} since device is not operated at $I_B=0$ in PA applications
- \checkmark f_{max} is a more useful figure-of-merit than f_T and SiGe HBT does not demand a rigid trade-off between BV_{CB0} and f_{max}

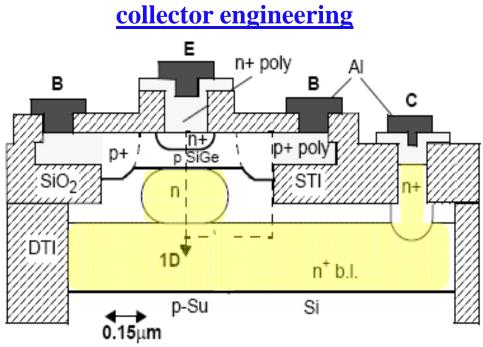
Unity current gain (cutoff) frequency

$$f_T = \frac{1}{2\pi\tau_f} = \frac{g_m}{2\pi C_{in}}$$

Unity power gain (maximum oscillation) frequency

$$f_{\text{max}} = \sqrt{\frac{f_T}{2\pi C_{bc} r_b}}$$



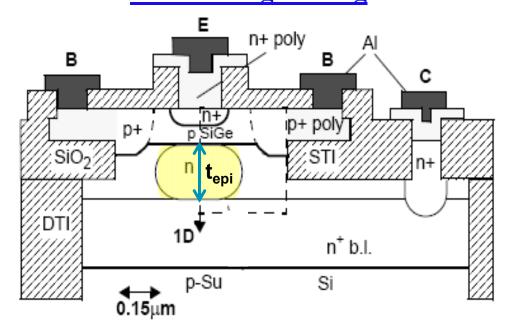


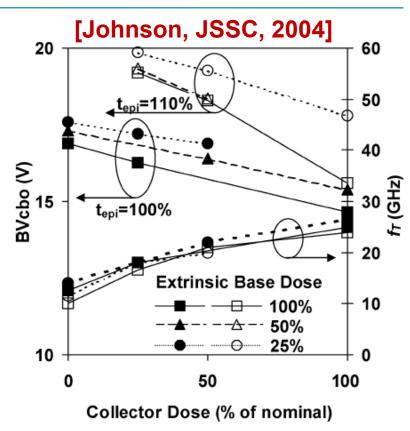
Bipolar Transistor	Collector doping	Collector thickness
Higher	faster, lower BV _{CB0}	slower, higher BV _{CB0}
Lower	slower, higher BV _{CB0}	faster, lower BV _{CB0}

very slow transistor is not useful in PA design



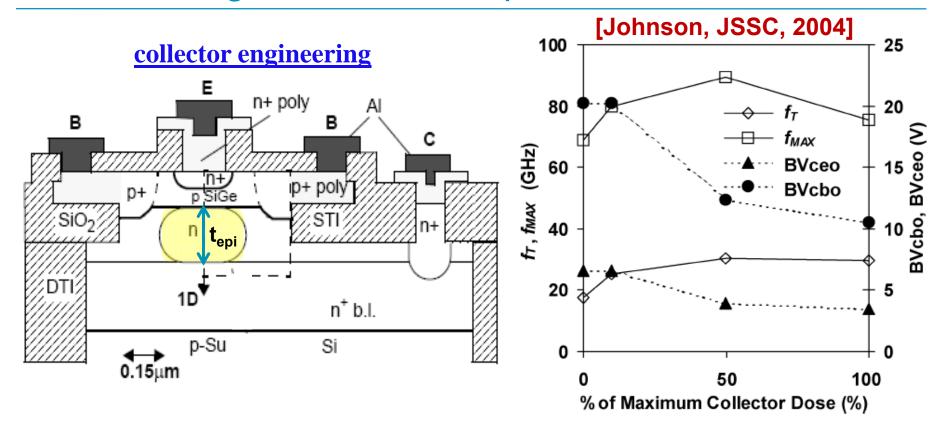
collector engineering





✓ significant opportunity to engineer SiGe HBT performance

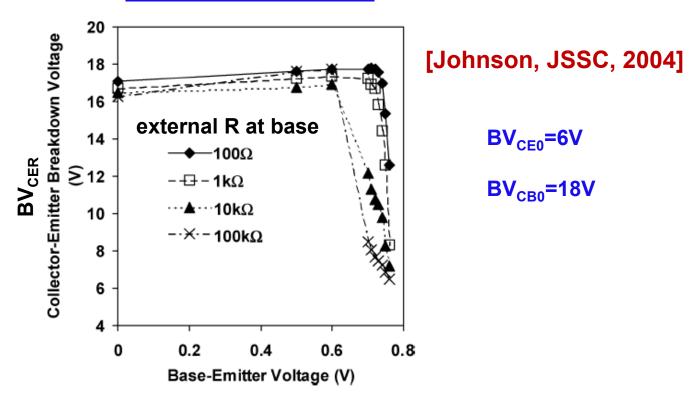




✓ significant opportunity to engineer SiGe HBT performance



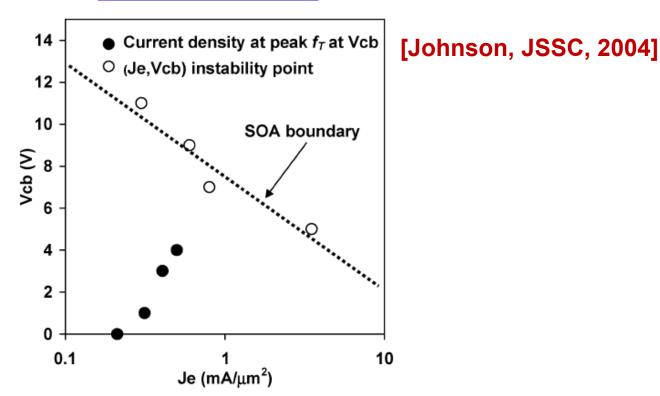
safe operating voltage



✓ R at base improves the breakdown voltage enormously



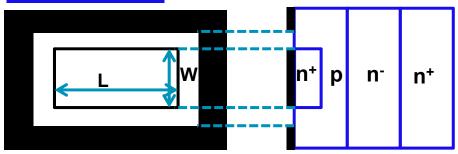
safe operating limit



✓ expected operating areas are well within the safe operating limits



scaling effects

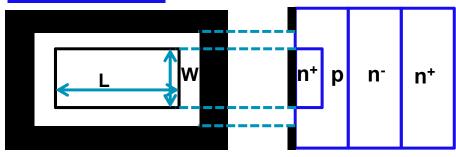


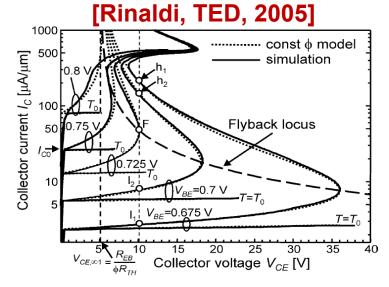


VCE, crit (V)

Device Design for Power Amplifier

scaling effects

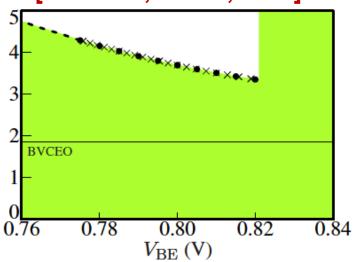




$$I_{CF} = \frac{\eta V_{T0}}{\phi R_{TH} V_{eq} - R_{eq}}$$

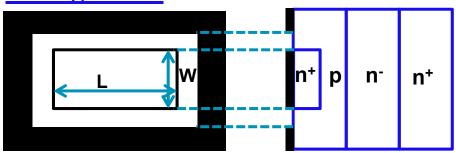
$$V_{BE} \downarrow I_{CF} \downarrow V_{CF} \uparrow$$

[Scholten, BCTM, 2012]





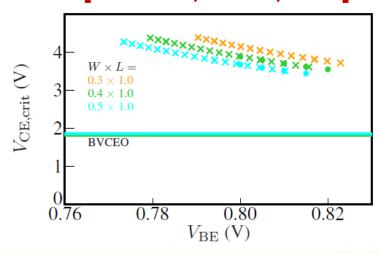
scaling effects



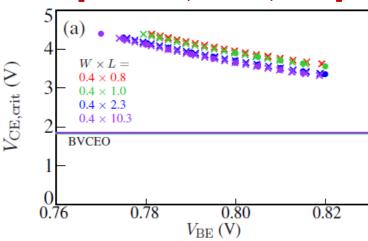
$$I_{CF} = \frac{\eta V_{T0}}{\phi R_{TH} V_{eq} - R_{eq}}$$

$$R_{TH} \propto \frac{1}{WL}, R_{B} \propto \frac{1}{L}$$

[Scholten, BCTM, 2012]



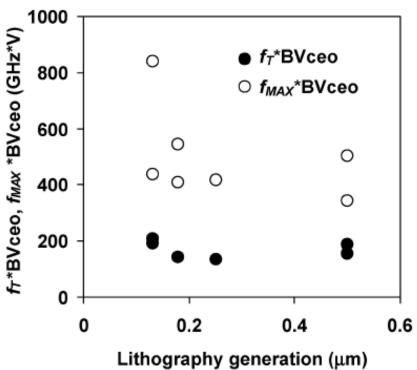
[Scholten, BCTM, 2012]





Device Design for Power Amplifier

technology scaling effects



[Johnson, JSSC, 2004]

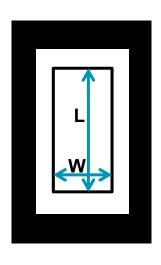
 \checkmark $f_{max}*BV_{CE0}$ is significantly improved with technology scaling



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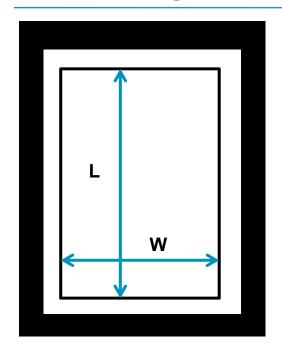




- **➤** Mainly evolved for PA applications
- \rightarrow High power application \rightarrow large A_E reqd.

$$A_E = WL$$

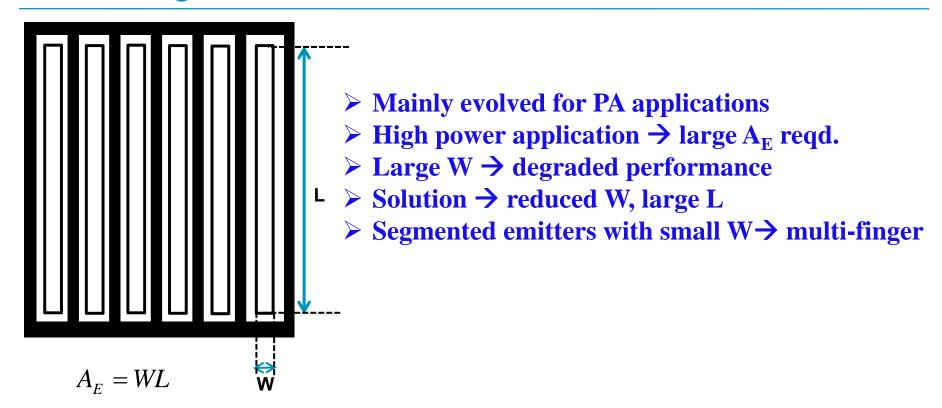




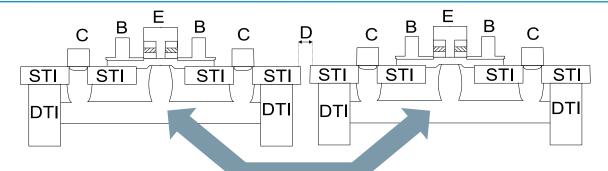
 $A_E = WL$

- **➤** Mainly evolved for PA applications
- \rightarrow High power application \rightarrow large A_E reqd.
- **>** Large W → degraded performance

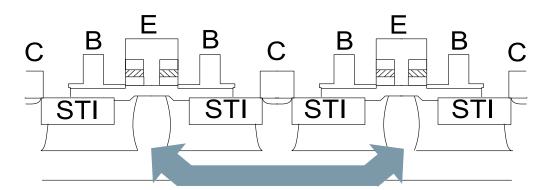






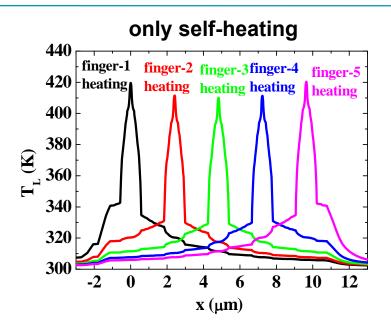


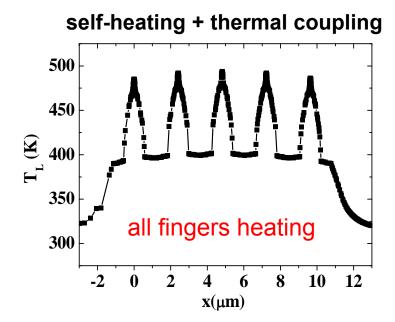
low inter-device thermal coupling



significant intra-device thermal coupling

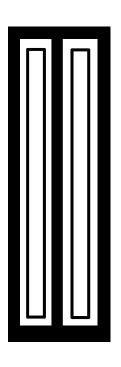


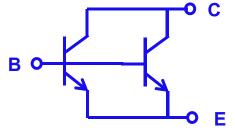




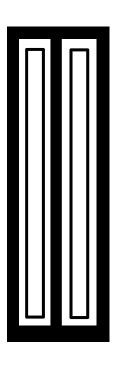
- \rightarrow finger-3 \rightarrow least self-heating but highest thermal coupling
- \rightarrow finger-1,5 \rightarrow highest self-heating, but least thermal coupling

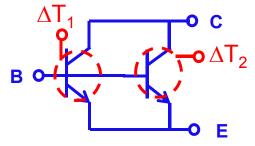




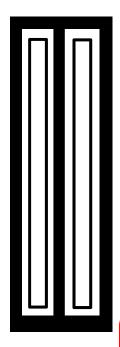












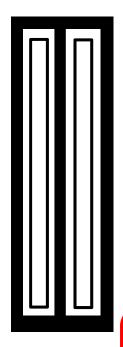
$$\Delta T_{1} = R_{TH,11} P_{diss,1} + R_{TH,12} P_{diss,2}$$

$$= R_{TH,11} V_{eq} I_{C1} + R_{TH,12} V_{eq} I_{C2}$$

$$\Delta T_2 = R_{TH,21} P_{diss,1} + R_{TH,22} P_{diss,2}$$

$$= R_{TH,21} V_{eq} I_{C1} + R_{TH,21} V_{eq} I_{C2}$$

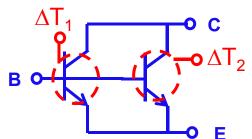




two finger device

identical fingers

$$egin{aligned} R_{TH\,,11} &= R_{TH\,,22} &= R_{TH} \ R_{TH\,,12} &= R_{TH\,,21} &= R_{M} \end{aligned}$$



normal operation

$$I_{C1} = I_{C2} = I_{C}$$
 $P_{diss,1} = P_{diss,2} = P_{diss}$

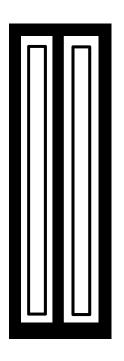
$$\Delta T_{1} = R_{TH,11} P_{diss,1} + R_{TH,12} P_{diss,2}$$

$$= R_{TH,11} V_{eq} I_{C1} + R_{TH,12} V_{eq} I_{C2}$$

$$\Delta T_2 = R_{TH,21} P_{diss,1} + R_{TH,22} P_{diss,2}$$

$$= R_{TH,21} V_{eq} I_{C1} + R_{TH,21} V_{eq} I_{C2}$$

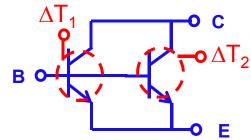




two finger device

identical fingers

$$R_{TH,11} = R_{TH,22} = R_{TH}$$
 $R_{TH,12} = R_{TH,21} = R_{M}$



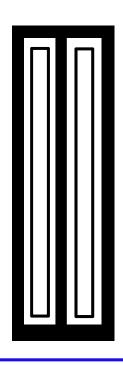
normal operation
$$I_{C1} = I_{C2} = I_{C}$$

$$P_{diss,1} = P_{diss,2} = P_{diss}$$

$$\Delta T_1 = \Delta T_2 = (R_{TH} + R_M) P_{diss}$$

electro-thermal behavior of each finger is identical to a single-finger device with a modified self-heating resistance!





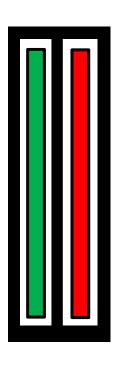
$$I_{CF} = \frac{\eta V_{T0}}{\phi (R_{TH} + R_M) V_{eq} - R_{eq}}$$

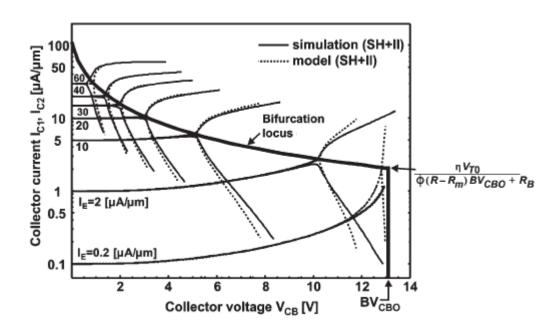
- ✓ flyback behavior of each finger is identical to a single-finger device!
- □ after a critical amount of current drive, it is likely that one of the fingers will carry most of the current causing a current bifurcation!

$$R_{TH,11} = R_{TH,22} = R_{TH}$$

 $R_{TH,12} = R_{TH,21} = R_{M}$

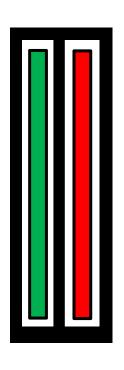




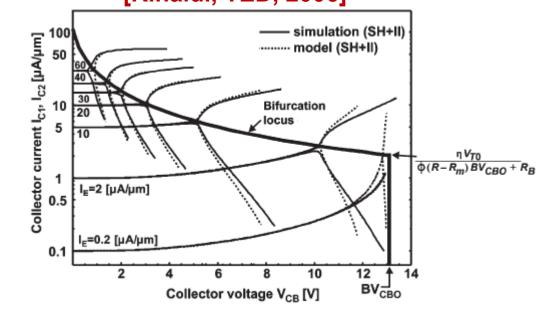


[Rinaldi, TED, 2006]





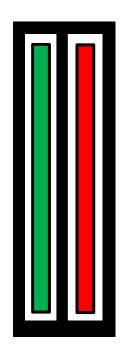
two finger device [Rinaldi, TED, 2006]



bifurcation locus

$$I_{CB} = \frac{\eta V_{T0}}{\phi (R_{TH} - R_{M}) V_{eq} - R_{eq}}$$





two finger device

bifurcation locus

$$I_{CB} = \frac{\eta V_{T0}}{\phi (R_{TH} - R_M) V_{eq} - R_{eq}}$$

flyback locus

$$I_{CF} = \frac{\eta V_{T0}}{\phi (R_{TH} + R_M) V_{eq} - R_{eq}}$$

- safe operating limit is determined by the flyback locus with V_{BE} excitation
- \checkmark with I_B and I_E excitation, no flyback occurs and the safe operating limit is determined by the bifurcation locus
- ✓ in case the limit is determined by the current bifurcation, thermal coupling improves the thermal stability!



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Summary

- ✓ Understanding safe operating limits is important for circuit design, especially the high power circuits
- ✓ Modeling of the locus for the safe operating limits primarily depends on electrothermal and impact ionization effects
- ✓ At lower current drive, impact ionization is the limiting factor whereas the electrothermal heating is the main concern in high current operation
- ✓ Formulation details and underlying physics are discussed with individual and concurrent presence of both the effects
- ✓ Device design aspects in view of power amplifier applications are discussed showing the opportunities of the advanced SiGe process
- ✓ Multi-finger transistors are presented as promising device for high power applications
- ✓ Safe operating limits of multi-finger devices are determined by flyback or bifurcation locus depending on the excitation condition



Acknowledgement

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THANK YOU